TeSys U starter-controllers



TeSys U starter-controller



Presentation

- The TeSys U starter-controller is a D.O.L. starter (1) which performs the following functions:
- Protection and control of single-phase or 3-phase motors:
- □ isolation and breaking function,
- overload and short-circuit protection,
- □ thermal overload protection,
- □ power switching.
- Control of the application:
- □ protection function alarms, application monitoring (running time, number of faults, motor current values, ...),
- □ logs (last 5 faults saved, together with motor parameter values).

These functions can be added by selecting control units and function modules which simply clip into the power base.

This late customisation is even possible after power and control circuit wiring has been completed.

TeSys U is a flexible range that meets the current and future needs of system builders, panel builders and machine manufacturers, as well as those of additional systems.

From design through to operation, TeSys U offers many advantages and simplifies the selection of components in comparison with a traditional solution. - the breaking, isolation and contactor functions are incorporated in a single block;

 the breaking, isolation and contactor functions are incorporated in a single block; this means fewer references to be ordered and easy selection without any risk of error, because a single reference covers all needs up to 15 Kw.

- the control unit has a wide setting range. It can operate on a d.c. or a.c. supply. The number of references required is divided by 10, compared with traditional solutions.

The compact components in the TeSys U range are mounted on a single rail, so optimising the amount of space required in enclosures. By eliminating power wiring between the circuit-breaker and contactor, TeSys U reduces installation times in enclosures.

Setting-up accessories simplify or completely eliminate wiring between components and eliminate the risk of errors.

Starter-controller

Consists of a power base and a control unit.

Power bases 1

The power base is independent of the control voltage.

It is available from 0 to 15 kW at 400 V.

It incorporates the breaking function with a breaking capacity of 50 kA at 400V, total coordination (continuity of service) and the switching function.

- 2 ratings are available: 0...12 A and 0...32 A.
- Non-reversing (LUB) and reversing (LU2B).

Control units 2

These must be selected according to the control voltage, the power of the motor to be protected and the type of protection required.

■ Standard control unit (LUCA): satisfies the basic protection requirements for motor starters: overload and short-circuit.

Magnetic control unit (LUCL): when fitted upstream of a variable speed drive or soft start-soft stop unit and used in conjunction with an LUB 12 or LUB 32 power base, this unit provides isolation and short-circuit protection of the motor starter.
 Advanced control unit (LUCB, LUCC or LUCD): allows additional advanced functions such as alarm, fault differentiation,...

Multifunction control unit (LUCM): suitable for the most sophisticated control and protection requirements.

The control units are interchangeable without rewiring and without using tools. They have a wide range of adjustment (range of 4) and low heat dissipation, due to the fact that bimetallic overload protection components are no longer used.

(1) For use with resistive and inductive loads. Control of d.c. or capacitive loads is not possible.

Presentation (continued)

TeSys motor starters - open version

TeSys U starter-controllers



Control options

Function modules can be used to increase the functions of the starter-controller.

Function modules 3

Must be used in conjunction with advanced control units.

- 4 types are available:
- Thermal overload alarm (LUF W10).
- Thermal fault and manual reset (LUF DH11).
- Thermal fault and automatic or remote reset (LUF DA01 and LUF DA10).

Indication of motor load (LUF V2), which can also be used in conjunction with the multifunction control unit.

All alarm and fault information processed by these modules is available on digital contacts.

Communication modules 3

- The information processed is exchanged:
- Via a parallel bus:
- □ parallel wiring module (LUF C00).
- Via a serial bus:
- □ AS-Interface modules (ASILUF C5 and ASILUF C51),
- □ Profibus DP module (LUL C07),
- □ CANopen module (LUL C08),
- DeviceNet module (LUL C09),
- □ Advantys STB module (LUL C15).
- □ Modbus modules (LUL C031 and LUL C033).

They must be used in conjunction with a --- 24 V control unit and require a --- 24 V supply voltage.

Connection to other protocols, such as Fipio, is possible via gateway modules (LUFP) or via the TeSysPort for Ethernet.

Auxiliary contact modules (LUFN) 3

3 possible configurations: 2 N/O, 1 N/O + 1 N/C or 2 N/C.

Auxiliary contacts 4

They provide the following information: fault signalling and rotary knob in "ready" Φ position.

Power options

Reverser block 5

Allows a non-reversing power base to be converted to reversing operation. The reverser block (LU2M) is mounted directly beneath the power base without modifying the width of the product (45 mm). The reverser block (LU6M) is mounted separately from the power base when the height available is limited.

Limiter-disconnector LUA LB

This unit is mounted directly on the power base. It allows the breaking capacity to be increased up to 130 kA at 400 V, with a visible break.

Setting-up accessories

Plug-in terminal blocks 6

The control terminal blocks are of the plug-in type, so allowing wiring to be prepared away from the machine or the replacement of products without rewiring.

Control circuit pre-wiring system 7

Numerous pre-wired accessories provide simple, clip-in connections, e.g. connection of reverser control terminals, ...



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Auxiliary contacts



Auxiliary contacts			
Number of contacts	2 -	1 1	- 2
Power pole status	NO NC	NO NC	NO NC
References	LUF N20	LUF N11	LUF N02
Signalling contacts			
Number of contacts		1 1	2 -
Fault signalling		NC (95-96)	NO (97-98)
Position of rotary knob		NO (17-18)	NO (17-18)
References		LUA 1C11	LUA 1C20

TeSys U starter-controllers



Note: the colour indicates possible combinations with the selected control unit. Example: function module LUF DH11 can only be used with an advanced control unit.

Advanced control unit

LUCB Class 10 - 3-phase

LUCC Class 10 - single-phase LUCD Class 20 - 3-phase (see page 1/69)

- Same functions as the standard control unit
- In addition, in conjunction with a function module:
- □ fault differentiation with manual reset,
- □ fault differentiation with remote or automatic reset,
- □ thermal overload alarm,
- □ indication of motor load.

Multifunction control unit



LUCM Classes 5 to 30 - single-phase and 3-phase (see page 1/70)

- Same functions as the standard control unit
- In addition, reset parameters can be set to manual or automatic.
- Protection function alarm.
- Indication on front panel or on remote terminal via Modbus RS 485 port.
- "Log" function.
- "Monitoring" function, indication of main motor parameters on front panel of the control unit, or via a remote terminal
- Differentiation of thermal overload and magnetic fault.
- Overload, no-load running.



AS-Interface communication modules (1) ASILUF C5 and ASILUF C51 (see page 1/78)

2

Profibus DP communication module (1) LUL C07 (see page 1/80)



CANopen communication module (1) LUL C08 (see page 1/84)



DeviceNet communication module (1) LUL C09 (see page 1/86)



1

Advantys STB communication module (1) LUL C15 (see page 1/90)



Modbus communication modules (1) LUL C031 and LUL C033 (see page 1/92)

(1) Communication modules can only be combined with a --- 24 V control unit (LUC• •• BL).

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TeSys motor starters - open version TeSys U starter-controllers





Application

Starting and protection of a pump.

Operating conditions

- Power: 4 kW at 400 V.
- In: 9 A.
- Maximum of 10 class 10 starts per hour.
- Duty class S3.
- 3-wire control:
- □ Start button (S2),
- \Box Stop button (S1),
- Control circuit voltage: ~ 230 V.

Products used

1 1000003 0360				
Description	ltem	Quantity	Reference	Page
Power base 12 A with screw clamp connections	1	1	LUB 12	1/62
Standard control unit	2	1	LUCA 12FU	1/69

Functions performed

■ Short-circuit protection with level of protection of 50 kA at 400V.

■ Total coordination of protection devices conforming to EN 60947-6-2 (continuity of service) in case of a short-circuit.

Electronic protection against thermal overloads with an adjustment range of 4.

Load switching (2 million operating cycles in category AC-43 at In).

■ Indication of motor status by N/C or N/O contact.

■ Interlock between the motor starter control and the position of the rotary knob; not possible to start the motor when the knob is in the OFF position.

Scheme



TeSys motor starters - open version

TeSys U starter-controllers



Application

Expansion of an existing installation for improved control of its operation.

Operating conditions

Monitor the status of the motor and obtain alarm signalling by a digital contact in order to improve operation of the pump and anticipate a complete stoppage due to thermal overload.

Additional products u	used			
Description	ltem	Quantity	Reference	Page
Replace the standard control overload alarm function mode		dvanced co	ntrol unit and inser	t a thermal
Advanced control unit	2	1	LUCB 12FU	1/69
Alarm function module	3	1	LUF W10	1/71

Functions performed

Alarm information is generated by the advanced control unit and is processed by the thermal overload alarm function module to make it usable.

The advanced control unit includes a thermal trip Test button on its front panel.

Scheme



Other versions

The advanced control unit can provide other functions, depending on the type of function modules used (instead of the LUF W module described above):

- thermal fault signalling with function modules LUF DA01, LUF DA10 or LUF DH11,

- indication of motor load with function module LUF V2. This module delivers a 4-20 mA analogue signal, which is proportional to the average 3-phase current drawn by the motor. This allows the load current to be monitored and provides access to other application functions using this value, or to predictive or preventive maintenance possibilities (replacement of the motor before it breaks down).

TeSys motor starters - open version TeSys U starter-controllers





Application

Manual control of a 2-position turntable.

Operating conditions

- Power: 2.2 kW at 400 V.
- In: 6 A.
- 30 starts per hour
- Duty class S4.
- 3-wire control:
- □ Pushbutton for Position 1 (S1),
- □ Pushbutton for Position 2 (S2),
- □ Stop button (S5),
- Stopping at the positions is achieved by limit switches S3 and S4.
- Control circuit voltage: \sim 115 V.

Products used

Description	Item	Quantity	Reference	Page
Power base, reversing, 12 A with screw clamp connections	1	1	LU2B 12FU	1/63
Standard control unit	2	1	LUCA 12FU	1/69

Functions performed

Short-circuit protection with level of protection of 50 kA at 400V.

■ Total coordination of protection devices conforming to EN 60947-6-2 (continuity of service) in case of a short-circuit.

- Electronic protection against thermal overloads with an adjustment range of 4.
- Load switching (2 million operating cycles in category AC-43 at In).

 Interlock between the motor starter control and the position of the rotary knob; not possible to start the motor when the knob is in the OFF position.

Electrical interlocking is ensured by pre-wired connector LU9M R1C included on base LU2B 12. The design of the reversing power block makes mechanical interlocking unnecessary.

Scheme (manual control)



TeSys motor starters - open version

TeSys U starter-controllers





10903

Modbus profile IEC 64915									
Commands (Register 704)		Status (Register 455)							
Forward running	Bit 0	Ready (available)							
Reverse running	Bit 1	Poles closed							
Reserved	Bit 2	Fault							
Reset	Bit 3	Alarms							
Reserved	Bit 4	Tripped							
Connection test	Bit 5	Reserved reset enabled							
Reserved	Bit 6	A1-A2 powered							
Reserved	Bit 7	Motor running							
Reserved	Bit 8	Motor current % (bit 0)							
Reserved	Bit 9	Motor current % (bit 1)							
Reserved	Bit 10	Motor current % (bit 2)							
Reserved	Bit 11	Motor current % (bit 3)							
Reserved 3-phase control	Bit 12	Motor current % (bit 4)							
Reserved	Bit 13	Motor current % (bit 5)							
Reserved	Bit 14	Reserved							
Reserved	Bit 15	Motor starting							

Application

Monitoring operation of a surface pump in a water treatment plant to avoid dry running, which could lead to destruction of the pump.

Operating conditions

- Power: 15 kW at 400 V.
- In: 28.5 A.
- Duty class S1.
- Control circuit voltage: --- 24 V.
- Control-command by PLC and serial link using the Modbus protocol.

Products used

FIDUUCIS USEU				
Description	ltem	Quantity	Reference	Page
Power base 32 A without connections	1	1	LUB 320	1/62
Multifunction control unit	2	1	LUCM 32BL	1/70
Modbus communication module	3	1	LUL C033	1/93
Pre-wired coil connection Connection of communication module output terminals to the coil terminals	4	1	LU9B N11C	1/93
Connection cable for connecting the communication module to the serial bus	-	1	VW3 A8 306 Ree	1/93
T-junction	_	1	VW3 A8 306 TF03	1/93

Functions performed

- Short-circuit protection with level of protection of 50 kA at 400V.
- Total coordination of protection devices conforming to EN 60947-6-2 (continuity of service) in case of a short-circuit.
- Electronic protection against thermal overloads with an adjustment range of 4.
- Load switching (1.5 million operating cycles in category AC-43 at In).
- Measurement of load current and detection of no-load running by the multifunction control unit.

■ Interlock between the motor starter control and the position of the rotary knob; not possible to start the motor when the knob is in the OFF position.

No-load running or operation under load. To use this function, the following parameters must be entered:

□ trip: the answer yes/no enables or disables the function,

□ time before tripping: the time period during which the value of the current must be below the tripping threshold in order to cause tripping (adjustable from 1 to 200 s),
 □ tripping threshold: value as a % of the load current ratio in relation to the setting current. If the ratio remains below this threshold for the time specified in the previous parameter, the product trips (adjustable from 30 to 100 %).

Indication of the various motor starter statuses and currents.

Schemes



Other functions

The multifunction control unit incorporates other control and protection functions, such as: monitoring and control of phase current, alarm, ...

Module LUL C033 also provides a programmable output and two configurable discrete inputs.

TeSys U starter-controllers Non-reversing power bases

1





LUB •2

LUB •20



■ connection by screw terminals, plug-in control terminal block,

■ without connections. This version enables wiring to be prepared in advance and is recommended when a communication module is required (allowing the use of control connection prewiring accessories) or when a reverser block is to be mounted by the customer.

Power bases for non-reversing D.O.L. starting (1)										
Connecti	on	Item	Rating			Reference	Weight			
Power	Control	(2)	≤ 440 V	500 V	690 V					
			A	Α	Α		ka			

These bases have 2 auxiliary contacts: 1 N/O (13-14) and 1 N/C (21-22) which indicate the closed or open position of the power poles.

A low power internal contact allows power supply to the control unit to be switched off when the rotary knob is no longer in the ON position.

The power bases must be used in conjunction with a control unit, see pages 1/68 to 1/70

Screw clamp	Screw clamp	1 + 2 + 3 + 4	12	12	9	LUB 12	0.900
terminals	terminals		32	23	21	LUB 32	0.900
	Without connections	1+2	12	12	9	LUB 120	0.865
			32	23	21	LUB 320	0.865

Terminal block for power bases without connections									
Connection	For base	ltem (2)	Reference	Weight kg					
Screw clamp terminals	LUB 120 or 320	3 + 4	LU9B N11	0.045					

(1) Rated breaking capacity for operation on short-circuit (Ics), see table below. For higher values, use current limiters, see page 1/66

Volts		230	440	500	690 (3)	
kA		50	50	10	4	

(2) The various sub-assemblies are supplied assembled but they are easy to separate, as shown in the illustration.

(3) For 690 V, use phase barrier LU9 SP0.

Other versions Power bases without built-in short-circuit protection device (short-circuit protection by circuit-breaker or separate fuses). Please consult your Regional Sales Office.

LUB • 2



Characteristics: pages 1/96 to 1/98

1/62

Schemes: pages 1/112 to 1/119

Schneider Electric

References

TeSys motor starters - open version

TeSvs U starter-controllers Reversing power bases

5 5





LU2B •2



LU6M + LU9 M1 + LU9M R1

Characteristics: Dimensions: Schemes pages 1/96 to 1/98 pages 1/110 and 1/111 pages 1/112 to 1/119

Schneider Electric



Two versions of control connection configuration are available: connection by screw terminals, plug-in control terminal block,

■ without connections. This version enables wiring to be prepared in advance and is recommended when a communication module is required (allowing the use of control connection prewiring accessories).

Power bases for reversing D.O.L. starting, pre-assembled									
Connection		Item	Rating			Reference, to	Weight		
Power	Control	(1)	≤440 V	500 V	690 V	be completed) (2)			
			Α	Α	Α		kg		
T I I		11/0				0.042 1.1.1.1.1.1			

These bases have two N/O common point contacts (81-82-84) which indicate nonreversing and reversing operating status.

Screw	Screw	1+2+3	12	12	9	LU2B 12••	1.270
clamp terminals	clamp terminals	+ 4 + 5	32	23	21	LU2B 32••	1.270
	Without	1+2+3	12	12	9	LU2B A0ee	1.270
	connections	+ 5	32	23	21	LU2B B0ee	1.250

Power bases for reversing D.O.L. starting for customer assembly

A reverser block should preferably be combined with a non-reversing power base without connections to create a reversing starter-controller.

The built-in N/O (13-14) and N/C (21-22) contacts are used for electrical interlocking between the reverser block and the base; they are therefore no longer available as output contacts.

The reverser block has two N/O common point contacts (81-82-84) which indicate non-reversing and reversing operating status.

32 A reverser block	Connection		Item (1)	Reference, to	Weight	
	Power	Control		be completed) (2)	kg	
For mounting directly beneath the power base	Screw clamp terminals	Without connections	3	LU2M B0●●	0.400	
For mounting separately from the base (screw or rail fixing)	Screw clamp terminals	Without connections	6	LU6M B0●●	0.425	

Accessories

A000330				
Description	Item	Application	Reference	Weight kg
Control terminal	4	Reversing power base without connections LU2B A0●● or B0●●	LU9 M1	0.025
block		Reverser block LU2M B0 for direct mounting beneath power based and the second second second second second second second second second	LU9 M1 se	0.025
		Reverser block LU6M B0•• for mounting separately from power b	LU9 M1 ase	0.025
	7	Reverser block LU6M B0 for mounting separately from power b	LU9M R1 ase	0.030

Control circuit pre-wiring components

		.			
Description			Item	Reference	Weight kg
Pre-wired connector (3	3)		5	LU9M R1C	0.035
(1) = (

(1) The various sub-assemblies are supplied assembled but they are easy to separate, as shown in the illustration.

(2) Select the same control voltage as that of the control unit.

Standard co	ntrol circuit voltages.		
Volts	24	4872	110240
==	BL	-	-
\sim	В	-	_
$=$ or \sim	_	ES (4)	FU (5)
(2) Ear control o	annoation botwoon a	nower base and a	reverser block for direct mounting

B) For control connection between a power base and a reverser block, for direct mounting. (4):: 48....72 V, ∼ : 48 V.

(5) == : 110…220 V, ∼ : 110…240 V. Other versions

Power bases without built-in short-circuit protection device (short-circuit protection by circuit-breaker or separate fuses). Please consult your Regional Sales Office.

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TeSys motor starters - open version TeSys U starter-controllers Add-on contact blocks and auxiliary contact modules

Contact states de	pending on the produ	ict s	tatus						
			Position of rotary knob	Indication on front panel	N/O pole contact	N/C pole contact	N/O contact any fault	N/C ontact any fault	♂ N/O contact product ready
References of add-on cor and auxiliary contact mod			-	-	-	LUF N11 31-32	LUA1 C20 97-98	LUA1 C11 95-96	LUA1 C20 17-18
Terminal referencing		or	-	-	-	LUF N02 31-32 41-42	LUA1 C200 No terminal block	LUA1 C110 No terminal block	LUA1 C200 No terminal block
		or	-	-	LUF N20 33-34 43-44	LUB9 N11 21-22	-	-	LUA1 C11 17-18
		or	-	-	LUF N11 43-44	-	-	-	LUA1 C110 No terminal block
		or	-	-	LUB9 N11 13-14	-	-	-	-
Off			OFF	0					
Ready to operate			$\mathbb{Q}^{\mathfrak{O}}$	0		t		t	
Start			$\mathbb{D}^{\mathbf{O}}$	1		P			
Tripped on short-circuit			TRIP	>>					
Tripped on thermal overload	Manual reset mode		TRIP	0				p	
	Automatic reset on thermal overload fault mode		¶ [©]	0					
	Remote reset mode		$\mathbb{D}^{\mathbf{O}}$	0					

N/O contact ______ in closed position.

N/C contact — in open position.

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TeSys motor starters - open version TeSys U starter-controllers Add-on contact blocks and auxiliary contact modules



LUB + LUA1 + LUF N + LUA 8E20

References				
Auxiliary contacts				
Signalling and composition	Cabling	Item	Reference	Weight kg
1 N/C fault signalling contact (95-96) and 1 N/O contact (17-18)	Screw clamp terminals	1+2	LUA1 C11	0.030
indicating rotary knob in "ready" position	Without connections	1	LUA1 C110	0.012
1 N/O fault signalling contact (97-98) and 1 N/O contact (17-18)	Screw clamp terminals	1+2	LUA1 C20	0.030
indicating rotary knob in "ready" position ${}^{m{O}}$	Without connections	1	LUA1 C200	0.012
2 N/O contacts Contacts open, rotary knob in "OFF" position O- Contacts closed, rotary knob	Screw clamp terminals	6	LUA8 E20	0.048

in "ready" position $\ensuremath{\mathfrak{O}}$

Auxiliary contact modules for connection by screw clamp terminals

Module with 2 contacts indicating the status of the starter-controller power poles Operation: \sim or = 24...250 V, I th: 5 A

Composition		ltem	Reference	Weight kg
2 N/O contacts (33-34 and 43-44)	3	LUF N20	0.050
1 N/C contact (3	1-32) and 1 N/O contact (43-44)	3	LUF N11	0.050
2 N/C contacts (31-32 and 41-42)	3	LUF N02	0.050
Accessories				
Description	For use on	ltem	Reference	Weight kg
Screw clamp terminal blocks	LUA1 C110	2	LU9B C11	0.022
	LUA1 C200	2	LU9B C20	0.022
Blanking covers	Location for auxiliary contact, communication or function module	4	LU9C 1	0.020
	Location for add-on contact blocks	5	LU9C 2	0.010

References

TeSys motor starters - open version TeSys U starter-controllers Power connection pre-wired system, limiter blocks and accessories









Description	Application	Pitch mm	Item	Sold in lots of	Unit reference	Weight kg
Sets of 3-pole	2 tap-offs	45	2	1	GV2 G245	0.036
63 A busbars	·	54	-	1	GV2 G254	0.038
	3 tap-offs	45	_	1	GV2 G345	0.058
		54	-	1	GV2 G354	0.060
	4 tap-offs	45	1	1	GV2 G445	0.77
		54	-	1	GV2 G454	0.085
	5 tap-offs	54	-	1	GV2 G554	0.100
Protective end cover	For unused busbar outlets	-	4	5	GV1 G10	0.005
Terminal block for supply to one or	Connection from the top	-	3	1	GV1 G09	0.040

more busbar sets

Pre-wired system for power connections up to 160 A

The busbar system can be screw-mounted onto any type of support.

Set of 4-pole b	ousbars:	3-phase + n	eutral or 3-phase +	- common	
Number of tap-offs at 18 mm intervals	ltem	Length	For mounting in enclosure width	Reference	Weight
		mm	mm		kg
18	5	452	800	AK5 JB144	0.900

Removable 3-phase power sockets

			-			
Number of points used on the busbar system	Thermal current	ltem	Cable lengths	Sold in lots of	Unit reference	Weight kg
2	16	6	200	6	AK5 PC13 (1)	0.040
	32	6	250	6	AK5 PC33 (1)	0.045
			1000	6	AK5 PC33L (1)	0.060

Limiter bloc	:ks an	d acc	essor	ries		
Application	ltem	Breal capa	cing city lq	Mounting	Unit reference	Weight
		≤ 440	≤ 440 V 690 V			
		kA	kA			kg
Limiter- disconnector (3) (5)	7 + 9	130	70	Direct on power base	LUA LB1 (2)	0.310
Current limiter (3)	8	100	35	Separate	LA9 LB920	0.320
Limiter cartridge	9	130	70	Limiter-disconnector	LUA LF1	0.135
Clip-in marker holder	-	-	-	On power base, on reverser block, on parallel link splitter box	LAD 90 (4)	0.001

 The rated peak current for power sockets AK5 PC●● is 6 kA.
 When used in association with power bases LUB●●, the prospective short-circuit current must not exceed 7 kA. (2) Supplied with limiter cartridge.

(3) These devices make it possible to increase the breaking capacity of the power base.

(4) Sold in lots of 100.

(5) The limiter must be mounted on an LUB or LU2B power base. The limiter can therefore not be common to several motor starters.

References (continued)

TeSys motor starters - open version TeSys U starter-controllers

TeSys U starter-controllers Power connection pre-wired system, limiter blocks and accessories



TeSys motor starters - open version TeSys U starter-controllers Control units

Operating characte		Standard	Advanced			Multifunction
		LUCA	LUCB	LUCC	LUCD	LUCM
hermal overload protectio	n					
Overcurrent protection		14.2 x the se	etting current			3 to 17 x the setting current
Short-circuit protection		14.2 x the m	ax. current			
Protection against phase lo	SS					
Protection against phase in	nhalanco	_				
Earth fault protection	libalance	_				
equipment protection only)						
Tripping class		10		10	20	530
Notor type		3-phase		Single-phase	3-phase	Single-phase and 3-phase
Thermal overload test funct	tion	_			<u> </u>	
Overtorque						
lo-load running						
_ong starting time						
Reset method	Manual					Parameters can be set
veset method	Automatic or remote		With functio	n module, or pa	arameters	Parameters can be set
			can be set v	ria the bus with	а	
			communica below.	tion module, se	e chart	Parameters can be set via the bus wi
			bolom.			a communication module (see below
Alarm		-	Thermal ov	erload alarm on	lv with	Possible for each type of fault.
			function module or communication			Indication on front panel of the contro
			module, see	e below.		unit, via remote terminal, via PC or vi PDA (1).
						With communication modules to mak
						use of these alarms via a bus, see below.
"Log" function		_				Log of the last 5 trips.
-						Number of starts, number of trips,
						number of operating hours.
'Monitoring" function						Display of main motor parameters on
						front panel of the control unit, via
						remote terminal, via PC or via PDA (1
With function mod Thermal overload alarm	uies (2)		With module			
Thermal overload signalling	n and manual reset	-		e LUF DH11		
	g ana manuar 1036t					
Fhermal overload signalling	g and automatic or remote reset		With module	es LUF DA01 a	nd	
ndication of motor load (an	alogue)	_	With module LUF V			
	en medule en vie Medhu					
Starter status (ready, runnir	on module or via Modbu		mmunication		(2)	
Reset method	·y, ·uuii)			can be set via	the bus	
Alarm			With module	es LUL C031, L	UL C033,	With module LUL C031, LUL C033,
_			LUL C15, L	UL C07, LUL [´] C	08 and	LUL C15, LUL C07, LUL C08 and
Remote reset via the bus		_	LUL C09 (tr	nermal overload	alarmoniy).	LUL C09 and Modbus port on the control unit
ndication of motor load						(alarm possible for all types of fault).
Fault signalling and differer	ntiation					
	monitoring of all functions					With modules LUL C031, LUL C033,
						LUL C15, LUL C07, LUL C08 and
'Log" function		_				
Remote programming and r "Log" function "Monitoring" function						LUL C09 and Modbus port on the control unit.

PDA: Personal Digital Assistant.
 Mounting possibilities: 1 function module or 1 communication module.

TeSys motor starters - open version TeSys U starter-controllers

Standard and advanced control units



LUCA •••• LUCB ••••



LUB •2 + LUCA ••••



LUB •2 + LUCB ••••

Description

- Extraction and locking handle 1
- 2 Test button (on advanced control unit only)
- 3 Ir adjustment dial
- Locking of settings by sealing the transparent cover 4 5 Sealing of locking handle

J Ocanny	J OF IOCKIN	gnanue				
Standa	ard cont	trol unit	s			
Maximum standard power ratings of 3-phase motors 50/60 Hz		Setting range	Clip-in mounting on power base	Reference, to be completed by adding the	Weight	
400/440 V		690 V		Rating	voltage code (1)	
kW	kW	kW	Α	Α		kg
Class 10	for 3-pha	ase motor	s			
0.09	-	-	0.150.6	12 and 32	LUCA X600	0.135
0.25	-	-	0.351.4	12 and 32	LUCA 1Xee	0.135
1.5	2.2	3	1.255	12 and 32	LUCA 05ee	0.135
5.5	5.5	9	312	12 and 32	LUCA 12.	0.135
7.5	9	15	4.518	32	LUCA 18ee	0.135
15	15	18.5	832	32	LUCA 3200	0.135

Advanced control units

Pressing the Test button on the front panel simulates tripping on thermal overload.

Class 10 for 3-phase motors

0.000	101010	maoo mou				
0.09	-	-	0.150.6	12 and 32	LUCB X6ee	0.140
0.25	_	-	0.351.4	12 and 32	LUCB 1Xee	0.140
1.5	2.2	3	1.255	12 and 32	LUCB 05ee	0.140
5.5	5.5	9	312	12 and 32	LUCB 1200	0.140
7.5	9	15	4.518	32	LUCB 18ee	0.140
15	15	18.5	832	32	LUCB 3200	0.140

Class 10 for single-phase motors

-	-	-	0.150.6	12 and 32	LUCC X6ee	0.140
0.09	_	_	0.351.4	12 and 32	LUCC 1Xee	0.140
0.55	-	-	1.255	12 and 32	LUCC 05ee	0.140
2.2	-	-	312	12 and 32	LUCC 1200	0.140
4	_	_	4.518	32	LUCC 18ee	0.140
7.5	-	-	832	32	LUCC 32.	0.140

Class 20 for 3-phase motors

0.09	-	-	0.150.6	12 and 32	LUCD X6ee	0.140
0.25	_	-	0.351.4	12 and 32	LUCD 1Xee	0.140
1.5	2.2	3	1.255	12 and 32	LUCD 05ee	0.140
5.5	5.5	9	312	12 and 32	LUCD 1200	0.140
7.5	9	15	4.518	32	LUCD 18ee	0.140
15	15	18.5	832	32	LUCD 3200	0.140

(1) Standard control circuit voltages:

Volts	24	4872	110240
	BL (2), (3)	-	-
\sim	В	-	-
$=$ or \sim	_	ES (4)	FU (5)

(2) Voltage code to be used for a starter-controller with communication module.

(3) d.c. voltage with maximum ripple of ± 10 %. (4) ---: 48...72 V, ∼: 48 V. (5) ---: 110...220 V, ∼: 110...240 V.

Characteristics: pages 1/96 and 1/99 ____

TeSvs U starter-controllers Multifunction control units





LUCM••BL



LUB •2 + LUCM ••BL



Description

- Extraction and locking handle 1
- 2 Built-in display window (2 lines, 12 characters)
- 3 4-button keypad
- ---- 24 V auxiliary power supply 4
- Modbus RS485 communication port. Connection by RJ45 connector. 5
- 6 Sealing of locking handle

The display window 2 and keypad 3 allow:

- in configuration mode: local configuration of protection functions and alarms,
- in run mode: display of parameter values and events.
- The Modbus communication port 5 is used to connect:
- an operator terminal.
- a PC,
- a Personal Digital Assistant (PDA).

Multifunction control units

Parameter entry, monitoring of parameter values and consultation of logs are carried out:

- either on the front panel, using the built-in display window/keypad,
- or via an operator terminal,
- or via a PC or a PDA with PowerSuite software,
- or remotely, via a Modbus communication bus.
- Programming of the product via the keypad requires a --- 24 V auxiliary power supply.

Maximum standard power ratings of 3-phase motors 50/60 Hz		f 3-phase motors range m		Clip-in mounting on power base	Reference (1)	Weight	
400/415 V	500 V	690 V		Rating			
kW	kW	kW	Α	Α		kg	
0.09	-	-	0.150.6	12 and 32	LUCM X6BL	0.175	
0.25	-	-	0.351.4	12 and 32	LUCM 1XBL	0.175	
1.5	2.2	3	1.255	12 and 32	LUCM 05BL	0.175	
5.5	5.5	9	312	12 and 32	LUCM 12BL	0.175	
7.5	9	15	4.518	32	LUCM 18BL	0.175	
15	15	18.5	832	32	LUCM 32BL	0.175	

TeSys U user's manual (2)							
Application	Language	Reference	Weight kg				
On CD-Rom	Multi-language (3)	LU9 CD1	0.022				

HMI terminal

This compact Magelis terminal enables the parameters of multifunction control unit LUCM to be read and modified.

It is supplied pre-configured to provide dialogue with 8 TeSys U starter-controllers (Modbus protocol, application pages and alarm pages loaded). Starter-controller alarm and fault management takes priority

	ann anu ia	uit manaye	ement takes priorit	у.	
Language	Display w	indow	Supply voltage	Reference	Weight kg
Multi-language (3)	4 lines of 20 charac	ters	 24 V	XBT NU400	0.150
Connecting ca	ble (4)				
Function		Length	Туре	Reference	Weight kg
Connects terminal XE to a multifunction con		2.5 m	SUB-D 25-way female - RJ45	XBT Z938	0.200

(1) Input voltage == 24 V with maximum ripple of ± 10 %.

(2) The CD-Rom contains user's manuals for the AS-Interface and Modbus communication modules, multifunction control units and gateway modules, as well as the gateway programming software. (3) English, French, German, Italian, Spanish

(4) If a terminal is used with several control units, this cable can be connected to a Modbus hub or to T-junctions (see page 1/93).

Schneider

TeSys U starter-controllers Function modules



Presentation. functions

PowerSuite software workshop



PowerSuite screen on PC

ATV31

Page utilisateu Réglages rapid

JOG

Réglages rapides Réglages Contrôle moteur

Configuration born Contrôle command

Configuration des

Limitation de cour

Choix vitesses p

Valeurs vitesses Injection de coura

533181

572706

Presentation

The PowerSuite software workshop for PC is a user-friendly tool designed for setting up the Schneider Electric control device motors:

- TeSys U starter-controllers
- TeSys T motor management systems
- Altistart soft start/soft stop units
- Altivar variable speed drives
- Lexium 05 servo drives

It includes various functions designed for setup phases such as:

- Preparing configurations
- Start-up
- Maintenance

To facilitate start-up and maintenance, the PowerSuite software workshop is compatible with the Bluetooth® wireless link.

Functions (1)

Preparing configurations

The PowerSuite software workshop can be used on its own to generate the device configuration, which can be saved, printed and exported to office automation software.

The PowerSuite software workshop can also be used to convert an Altivar 58 or Altivar 58F drive configuration into one that is compatible with an Altivar 71.

Start-up

When the PC is connected to the device, the PowerSuite software workshop can be used to:

- Transfer the generated configuration
- Adjust
- Monitor. This option has been enhanced with new functions such as:
- □ The oscilloscope
- □ The high-speed oscilloscope (minimum time base: 2 ms)
- □ The FFT (Fast Fourier Transform) oscilloscope
- □ Display of communication parameters
- Control

Non configuré

1.00

1.00

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-

^

Save the final configuration

Maintenance

To facilitate maintenance operations, the PowerSuite software workshop can be used to:

- Compare the configuration of a device currently being used with a saved configuration
- Manage the user's installed equipment base, in particular:
- □ Organize the installed base into folders (electrical equipment, machinery,
- workshops, etc.)
- □ Store maintenance messages
- □ Facilitate Modbus TCP connection by storing the IP address

User interface

The PowerSuite software workshop can be used to:

- Present the device parameters (arranged by function) in the form of illustrated views of diagrams or simple tables
- Customize the parameter names
- Create:
- □ A user menu (choice of particular parameters)
- □ Monitoring control panels with graphic elements (cursors, gauges, bar charts)
- Perform sort operations on the parameters
- Display text in five languages (English, French, German, Italian and Spanish). The
- language changes immediately and there is no need to restart the program.
- It also features online contextual help:
- On the PowerSuite tool
- On the device functions by direct access to the user manuals
- (1) Certain functions are not available for all devices. See the table of available functions, page 1/73.

■●■●☆↓:4×●25× ■●■●☆↓:4×●25× D_NACT _ALM
 D_NET _ALM
 D_XET _ALM C Full F. **1**°

References page 1/74

1/72

Schneider

View of the FTT oscilloscope

1.0 Régulateur Pl FBS Coefficient retour PowerSuite screen on PC View of PI regulator function parameters

PIF Affectation Retour PI

RPG Gain proportionnel P

RIG Gain intégral PI

Functions available for the PowerSuite software workshop

Function available with devices	Controller	Starter- controller	Soft start/ soft stop unit	Drives	Drives			Servo drive
	TeSys T	TeSys U	ATS 48	ATV 11	ATV 31	ATV 61	ATV 71	LXM 05
Monitoring								
Oscilloscope								
High-speed oscilloscope								
FFT oscilloscope								
Display of communication parameters								
Control								
Customization of parameter names								
Creation of a user menu								
Creation of monitoring control panels								
Sort operation on parameters								
Custom logic editor								

Lexium 05

Modbus multidrop connection



Connections (1)

Modbus serial link

The PowerSuite software workshop can be connected directly to the device terminal port or Modbus network port via the serial port on the PC.

Two types of connection are possible:

Functions not available

■ With a single device (point-to-point connection), use a VW3 A8 106 PC serial port connection kit.

■ With a number of devices (multidrop connection), use the XGS Z24 interface.

Modbus TCP communication network

The PowerSuite software workshop can be connected to a Modbus TCP network. In this case, the devices can be accessed:

- Using a VW3 A3 310 communication card for the Altivar 61and 71 drives
- Using a TSX ETG 100 Modbus TCP/Modbus gateway

Bluetooth® wireless link

The PowerSuite software workshop can communicate via a Bluetooth[®] radio link if the device is equipped with a Bluetooth[®] Modbus VW3 A8 114. The adapter plugs into the device connector terminal port or Modbus network port and has a range of 10 m (class 2).

If the PC does not feature Bluetooth $^{\!\otimes}$ technology, use the VW3 A8 115 USB - Bluetooth $^{\!\otimes}$ adapter.

Remote maintenance

A simple Modbus TCP connection is all that is required for the PowerSuite software workshop to support remote monitoring and diagnostics.

When devices are not connected to the Modbus TCP network, or it is not directly accessible, various remote transmission solutions may be used instead (modem, teleprocessing gateway, etc.). Please consult your Regional Sales Office.

(1) Please refer to the compatibility table on page 1/75.
 (2) Please refer to our specialist "Automation platform Modicon Premium and Unity - PL7 software" and "Automation platform Modicon M340" catalogues.

Modbus	TCP	conne	ction
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Presentation:

page 1/72

References: page 1/74

PowerSuite software workshop

1

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VW3	A8	104



VW3 A8 114

Description	Composition	Reference	Weight kg
PowerSuite CD-ROM	 1 program for PC in English, French, German, Italian and Spanish Variable speed drive, starter and servo drive technical manuals 	VW3 A8 104	0.100
PowerSuite update CD-ROM (1)	 1 program for PC in English, French, German, Italian and Spanish Variable speed drive and starter technical manuals 	VW3 A8 105	0.100
PC serial port connection for point-to-point Modbus connection	 kit 1 x 3 m cable with 1 RJ45 connector on starter-controller or drive side and 1 RS 232/RS 485 converter with 1 9-way female SUB-D connector on PC side For the ATV 11 drive: 1 converter with one 4-way male SUB-D connector and 1 RJ45 connector For ATV 38/58/58F drives: 1 RJ45/9-way male SUB-D adapter 	VW3 A8 106	0.350
RS 232/RS 485 interface for multidrop Modbus connection	■ 1 Modbus multidrop converter for connection to screw terminals. Requires a 24 V (2030 V), 20 mA power supply (2)	XGS Z24	0.105
Modbus-Bluetooth® adapt (3)	er ■ 1 Bluetooth [®] adapter (10 m range, class 2) with 1 RJ45 connector ■ For PowerSuite: 1 x 0.1 m cable with 2 RJ45 connectors ■ For TwidoSoft: 1 x 0.1 m cable with 1 RJ45 connector and 1 mini DIN connector ■ For ATV 38/58/58F drives: 1 RJ45/9-way male SUB-D adapter	VW3 A8 114	0.155
USB - Bluetooth [®] adapter PC	For This adapter is required in the case of a PC that does not feature Bluetooth® technology. It is connected to a USB port on the PC. 10 m range (class 2)	VW3 A8 115	0.290

(1) Updates a version ≥ V1.40 with the latest available version. For versions < V1.40, you should order the PowerSuite CD-Rom, VW3 A8 104.

(2) Please refer to the "Interfaces, I/O splitter boxes and power supplies" catalogue.
 (3) Can also be used to communicate between a Twido PLC and the TwidoSoft software workshop.

Presentation: page 1/72

Connexion	Controller	Starter- Soft start/ Drives controller soft stop unit				Servo drives				
	TeSys T	TeSys U (2)	ATS 48	ATV 11	ATV 31	ATV 61	ATV 71	LXM 05A	LXM 05B	LXM 05C
Modbus	V2.5	V1.40	V1.30	V1.40	V2.0	V2.3	V2.2	V2.2	V2.4	V2.5
Modbus TCP (device equipped with Modbus TCP card)						V2.3	V2.2			
Modbus TCP via Modbus TCP/Modbus gateway			V1.50		V2.0	V2.3	V2.2	V2.2	V2.4	V2.5
Bluetooth®			V2.2		V2.2	V2.3	V2.2	V2.2	V2.4	V2.5

Incompatible software versions

Hardware and software environments

The PowerSuite software workshop can operate in the following PC environments and configurations:

■ Microsoft Windows® XP SP1, SP2,

■ Pentium III, 800 MHz, hard disk with 300 MB available, 128 MB RAM

SVGA or higher definition monitor

(1) Minimum software version. (2) TeSys U starter-controller without communication module or with Modbus LUL C031 or LUL C033 communication module.

Presentation:	Functions:	References:	
page 1/72	page 1/72	page 1/74	

TeSys U starter-controllers Parallel wiring module and pre-wired coil connection components





- 1 Outputs for starter commands
- 2 RJ45 connector for connecting to splitter box



510917



LU9 G03

Presentation

The parallel wiring system makes it possible to connect starter-controllers to the PLC I/O modules quickly and without any need for tools. It replaces traditional screw terminal and single wire connections. It is used with the Telefast pre-wired system (1).

The parallel wiring module provides the status and command information for each starter-controller. It must be used with an LUB 12 or LU2B A0BL power base and a ---- 24 V control unit LUC• ••BL.

Splitter boxes LU9 G02 and LU9 G03 distribute information from the PLC I/O modules to each of the starter-controllers connected to it.

Splitter box LU9 G02 (maximum of 4 reversing starters) is optimised for use with card TSX DMZ28DTK and splitter box LU9 G03 (maximum of 8 reversing starters) for use with cards TSX DMZ64DTK and BMX DDM3202K.

When used in conjunction with the Advantys STB distributed I/O solution, the TeSys U starter-controller is ideal in decentralised automation architectures (2). The use of dedicated parallel interface module STB EPI 2145 allows remote connection of 4 starter-controllers.

Parallel wiring module LUF C00 has:

Parallel type connection

Architecture

- 2 outputs: control of starter forward and reverse running,
- 3 inputs: position of the rotary knob, fault indication and position of the poles.

Each of the channels of LU9 GO• splitter boxes has:

■ 2 outputs: control of starter forward and reverse running, in the case of a reversing starter.

2 inputs: fault indication and position of poles.

Connection to the dedicated module is by means of the following cables:

- RJ45 LU9R●, for lengths less than 3 metres,
- 490 NTW 000●●, for lengths greater than 3 metres.



- 3 Parallel wiring module LUF C00
- Pre-wired coil connection LU9B N11C
- 5 Connection cable LU9 Re with one RJ45 connector at each end
- 6 Splitter box LU9 G02 or LU9 G03 for 8 motor starters with channel connections on the PLC side by two HE 10 connectors and on the startercontroller side by 8 RJ45 connectors.

Connection cable TSX CDP••• with one HE 10 connector at each end.

References			
Description	ltem	Reference	Weight kg
Parallel wiring module	3	LUF C00	0.045

Please consult our "Power Control and connection components catalogue".
 Please consult our "IP20 distributed inputs/outputs Advantys STB" catalogue

- 8 Dedicated parallel interface module (STB EPI 2145)
- 9 Power base
- 10 == 24 V control unit (LUC B/D/C/M •• BL)
- 11 Parallel wiring module (LUF C00)
- 12 Options: add-on contact blocks, reverser blocks

References (continued)

TeSys motor starters - open version

TeSys U starter-controllers Parallel wiring module and pre-wired coil connection components



LU2B + LUF C00 + LU9M

Pre-wired components simplify wiring and reduce wiring errors.

Connection of communication module output terminals to the coil terminals

By pre-wired connector or wire link.

Pre-wired connector: pre-wired coil connection

The use of a power base without pre-wired connections is recommended.

Description	For use with power base	ltem	Reference	Weight kg
Pre-wired coil connection	LUB ●●	4	LU9B N11C	0.045
	LU2B ●●	13	LU9M RC	0.030

Wire link:

Allows insertion, for example, of an emergency Stop control or a voltage interface. This type of connection must be used for a reversing starter-controller assembled using an LU6M reverser block for separate mounting. When reverser block LU6M and the power base are mounted side-by-side, a pre-wired coil connection LU9M RC may by used.

Connection of parallel wiring module to the PLC

No tools are required to connect the parallel wiring module to the PLC. Connection is via a splitter box which allows up to 8 starter-controllers to be connected; a maximum of 4 reversing starters per splitter box is allowed. The splitter box requires a --- 24 V power supply.

Splitter boxes				
Connectors		For use with	Reference	Weight
PLC side	Starter-controller side			kg
2 x HE 10 20-way	8 x RJ45	4 reversing starters maximum	LU9 G02 (1)	0.260
		8 reversing starters maximum	LU9 G03 (1)	0.260
Connection cabl	es to the splitter b	хох		
Connectors	Item	Length	Reference	Weight
		m		kg
2 x RJ45 connectors	s <u>5</u>	m 0.3	LU9 R03	к <u>д</u> 0.045
2 x RJ45 connectors	5		LU9 R03 LU9 R10	-
2 x RJ45 connectors	5	0.3		0.045
2 x RJ45 connectors Connection cabl		0.3 1 3	LU9 R10	0.045 0.065

PLC side	Splitter bo side	x				
		AWG	mm ²	m		kg
HE 10	HE 10	22	0.324	0.5	TSX CDP 053	0.085
20-way	20-way			1	TSX CDP 103	0.150
				2	TSX CDP 203	0.280
				3	TSX CDP 303	0.410
				5	TSX CDP 503	0.670
		28	0.080	1	ABF H20 H100	0.080
				2	ABF H20 H200	0.140
				3	ABF H20 H300	0.210
HE 10	2 x HE 10	_	0.324	0.5	BMX FCC 053	0.210
40-way	20-way			1	BMX FCC 103	0.350
				2	BMX FCC 203	0.630
				3	BMX FCC 303	0.940
				5	BMX FCC 503	1.530
				10	BMX FCC 1003	3.000
Bare wires	HE 10	22	0.324	3	TSX CDP 301	0.400
	20-way			5	TSX CDP 501	0.660

 Allows "run" and "fault" status of each starter-controller to be fed back to the PLC and transmits commands.

TeSys U starter-controllers AS-Interface communication modules



- 1 Green LED: AS-Interface voltage present
- 2 Red LED: AS-Interface or module fault
- 3 Outputs for starter commands
- 4 Black connector for connection to --- 24 V auxiliary power supply
- 5 Yellow connector for connection to the AS-Interface system

Presentation

AS-Interface communication modules ASILUF C5 and ASILUF C51 make it easy to connect starter-controllers to the AS-Interface cabling system, and therefore allow remote control and command of these starter-controllers.

Module ASILUF C51 features extended addresing.

The various operating states of the modules (AS-Interface voltage present, communication fault, addressing fault,...) are indicated on the front panel by a green LED 1 and a red LED 2.

Operation of the modules is continuously monitored by auto-testing, in a way that is totally transparent to the user.

The incorporation of AS-Interface V.2.1 functions allows diagnostics to be performed on the modules, either remotely via the line or locally via the ASI TERV2 addressing terminal.

The communication modules must be connected to a -24 V auxiliary supply and must be used in conjunction with a -24 V control unit, LUC•••BL. The product is supplied with a yellow connector 4 for connection to the AS-Interface system, a black connector 5 for connection to the -24 V auxiliary supply and a black connector 3 for connection of the outputs.



Architecture

- 6 Communication modules ASILUF C5 or ASILUF C51
- 7 Tap-off TCS ATV01N2
- 8 Pre-wired coil connection LU9B N11C



Information transmitted by the AS-Interface

62 slaves

AS-Interface profiles		7.D.F.0 profile and 7.A.7.E profile				
Data bits (command)	Bit value	= 0	= 1			
	Command D0 (O)	Stop forward	Forward ru	nning		
	Command D1 (O)	Stop reverse	Reverse ru	nning		
	Command D2 (O)	Not used	Not used			
	Command D3 (O)	Not used	Not used			
Data bits	Bit value	= 0	= 1			
(status)	Status D0 (I)	Not ready or fau	lt Ready			
	Status D1 (I)	Stopped	Running			
	Status D2 (I)	Not used	Not used			
	Status D3 (I)	Not used	Not used			
References						
Description	Addressing	Item	Reference	Weight kg		
Communication modules	Single 31 slaves	6	ASI LUF C5	0.065		
	Extended	6	ASI LUF C51	0.065		

References (continued)

TeSys motor starters - open version

TeSvs U starter-controllers

AS-Interface communication modules



LUB + ASILUF C5 + LU9B



LU2B + ASILUF C5 + LU9M

20899







ASI TERV2

Pre-wired components simplify wiring and reduce wiring errors.

Connection of communication module output terminals to the coil terminals

By pre-wired connector or wire link.

Pre-wired connector: pre-wired coil connection

The use of a power base without pre-wired control circuit connections is recommended.

Description	For use with power base	Item	Reference	Weight kg
Pre-wired coil connection	LUB ●●	3	LU9B N11C	0.045
	LU2B ●●	5	LU9M RC	0.030

Wire link

Allows insertion, for example, of an emergency Stop control or a voltage interface. This type of connection must be used for a reversing starter-controller assembled using an LU6M reverser block for separate mounting. When reverser block LU6M and the power base are mounted side-by-side, a pre-wired coil connection LU9M RC may be used.

Connection of the communication module (1)

This is achieved by using a tap-off for connection to 2 ribbon cables:

1 for AS-Interface (yellow).

1 for separate == 24 V supply (black).

Description	Length m	Reference	Weight kg
Tap-off	2	XZ CG0142	0.265

Consoles and cable adapter		
Description	Reference	Weight kg
Addressing terminal Battery operated. Battery charger supplied AS-Interface V.1 and V.2.1 compatible	XZ MC11	0.550
Adjustment and diagnostics console Runs on LR6 batteries Allows addressing of AS-Interface V.2.1 slaves and diagnostics	ASI TERV2	0.500
Cable adapter For console XZ MC11	XZ MG12	0.070

Software set-up

AS-Interface configuration is carried out using PL7 Micro/Junior/Pro software. From the module declaration screen, it is possible to configure all the slave devices corresponding to all the AS-Interface I/O.

Configuration is carried out by following the instructions on the screen.

TeSys U user's manual (2)			
Application	Language	Reference	Weight kg
On CD-Rom	Multi-language (3)	LU9 CD1	0.022

(1) Degree of protection IP 54. Connection by 4 x 0.34 mm² wires.

Black wire: + 24 V.

White wire: 0 V.

- Blue wire: AS-Interface (–). Brown wire: AS-Interface (+).

(2) The CD-Rom contains user's manuals for the AS-Interface and Modbus communication modules, multifunction control units and gateway modules, as well as the gateway programming software.

(3) English, French, German, Italian, Spanish

1

TeSys motor starters - open version

TeSys U starter-controllers Profibus DP communication module and pre-wired coil connection components



- 1 LED indicating module status
- 2 Fault signalling LED
- 3 LED indicating ---- 24 V supply ON for outputs OA1, OA3 and LO1
- 4 SUB-D connector for bus link
- 5 == 24 V supply connection
- 6 Discrete input
- 7 Discrete input
- 8 Discrete output
- Outputs for starter-controller commands (nonreversing and reversing)
- Pin for connection to control unit (advanced or multifunction)

Presentation

When used in conjunction with the power base and control unit, communication module LULC07 allows TeSys U starter-controllers to be controlled via Profibus DP (Deported Periphery).

Communication module LULC07 is of the slave type and uses the TeSys U system's internal registers (which can be accessed via the Profibus DP bus) in cyclic or acyclic mode. This module has a 24 V (0.5 A) discrete output and two configurable discrete inputs.

Connections

Serial bus topology



- 11 Programmable controller with Profibus DP master card
- 12 Other slave (not powered via the bus)
- 13 Profibus DP 2-wire cable (TSX PBSCA100 = 100 m, TSX PBSCA400 = 400 m)
- 14 Standard Profibus DP connector (490NAD91103 or 490NAD91104)
- 15 Profibus DP power supply module for == 24 V-Aux supply to LUL C07 modules (LU9 GC7)
- 16 Profibus DP connector, TeSys U dedicated (LU9 AD7)
- 17 Profibus DP 4-wire cable (LU9 RPB●●●)
- **18** Profibus DP communication module (LUL C07)

Profibus DP: general information

The TeSys U communication module supports 2 Profibus application profiles based on DP V0 and DP V1 services: motor starter (MS), motor management starter (MMS).

Cyclic / Acyclic services

In general, data is exchanged via cyclic services and via acyclic services.

- The application profiles define, for the cyclic data:
- manufacturer independent data,
- manufacturer specific data.

DP V1 Read / Write services

DP V1 read and write services allow access to all data that cannot be accessed by cyclic data exchange.

PKW feature

In order to make data which is not cyclically exchanged accessible for DP V0 masters, a function called PKW (Periodically Kept in acyclic Words) is implemented. The cyclic data carries a dedicated zone of 4 input words and 4 output words, called PKW, which makes it possible to access all the registers "en bloc".

Electronic device description

The TeSys U system is described by a GS*- file (1). This file will be used by any Profibus configuration tool to get information about the device.

The GS*- files and associated icon, dedicated to the TeSys U system, can be downloaded from the "www.schneider-electric.com" website (Library / Software Tools).

(1) Replace the asterisk with the letter corresponding to the required language.

Presentation (continued) references

TeSys motor starters - open version

TeSys U starter-controllers Profibus DP communication module and pre-wired coil connection components



LUL C07



Information carried by the bus

Depends on the type of control unit used with module LUL C07.

with 24 V control units Information accessible via Profibus DP	LUL C07 in conjunction with:			
	LUCA ••BL		LUCM ••BL	
	Standard control unit	Advanced control unit	Multifunction control unit	
Starter status (ready, running, fault)				
Start and Stop commands				
Thermal overload alarm				
Remote reset via the bus				
Indication of motor load				
Fault signalling and differentiation				
Remote programming and monitoring of all functions				
"Log" function				
"Monitoring" function				
Alarms (overcurrent,)				

References			
Description	Item	Reference	Weight kg
Profibus DP communication module	18	LUL C07	0.108

Connection of communication module output terminals to the coil terminals

By pre-wired connector or wire link.

Pre-wired connector: pre-wired coil connection

The use of a power base without pre-wired control circuit connections is recommended.

Description	For use with power base	Item	Reference	Weight kg
Pre-wired coil connection	LUB 🐽	4	LU9B N11L	0.050
	LU2B ●●	6	LU9M RL	0.450

Wire link:

Allows insertion, for example, of an emergency Stop control or a voltage interface. This type of connection must be used for a reversing starter-controller assembled using an LU6M reverser block.

When this reverser block and the power base are mounted side-by-side, a pre-wired coil connection LU9M RL may be used.

Components for connection to the bus and to the installation

The ---- 24 V-Aux supply to Profibus DP modules LUL C07 must pass through power supply module LU9 GC7.

LUL C07 modules must be connected to the LU9 GC7 splitter box in order to be powered.

The number of TeSys U starter-controllers that can be powered by an LU9 GC7 module is limited by the maximum current (1.5 A) which it can deliver. The -- 24 V supply for the inputs/outputs must be provided separately.

Description	Length m	ltem (1)	Reference	Weight kg
Profibus DP power supply module	-	15	LU9 GC7	-
Profibus DP connector	-	16	LU9 AD7	_
Profibus DP cables	100	13	TSX PBSCA100	_
2-wire	400	13	TSX PBSCA400	_
Profibus DP cables	10	17	LU9 RPB010	_
4-wire	100	17	LU9 RPB100	_
	400	17	LU9 RPB400	_

(1) See connection diagram on page 1/80.

TeSys U starter-controllers Profibus DP communication module and pre-wired coil connection components



Note: Profibus DP module LUL C07 is not compatible with LUT M controllers.

TeSys U starter-controllers Profibus DP communication module and pre-wired coil connection components



Note: Profibus DP module LUL C07 is not compatible with LUT M controllers.

TeSys U starter-controllers CANopen communication module and pre-wired coil connection components

1



- 1 LED indicating module status
- 2 Fault signalling LED
- 3 LED indicating ---- 24 V supply ON for outputs OA1, OA3 and LO1
- 4 SUB-D connector for bus link
- 5 == 24 V supply connection
- 6 Discrete input
- 7 Discrete input
- 8 Discrete output
- 9 Outputs for starter commands
- CANopen master module TSX CPP110 (PMCIA card with junction box).
- 11 Cable TSX CANC. equipped with a TSX CANKCDF90T connector (to be assembled)
- 12 Terminal block TSX CANTDM4 with 4 SUB D type connectors for connection of slaves and screw terminal blocks (connection of bus and dedicated 24 V supply to modules LUL C08).
- 13 Connection between junction boxes TSX CANTDM4 by cable TSX CANCADD...or cable TSX CANC...fitted with TSX CANKCDF90T connectors.
- 14 The slaves are connected by means of cables TSX CANCADD●●
- 15 Connections are made by means of cables TSX CANC. fitted with TSX CANKCDF180T connectors for the slaves and with TSX CANKCDF90T connectors for the junction boxes.
- 16 Starter-controller
- 17 CANopen communication module LUL C08
- 18 Advantys STB island (NIM: Network Interface Modules + I/O modules)
- 19 CANopen extension module STB XBE 2100K

Presentation

Communication module LUL C08 allows direct connection of TeSys U startercontrollers and controllers on a CANopen bus. Module LUL C08 is of the slave type.

When used in conjunction with an LUC •••BL or LUC •T1BL control unit, module LUL C08 provides control and command of the starter-controller and of the controller.

For local control requirements, the module is equipped with a configurable, --- 24 V. 0.5 V discrete output and two configurable discrete inputs.

LUL C08 communication modules can be connected to Advantys STB module : XBE 2100K.

Connections



Connection of power supplies

The $\frac{1}{2}$ 24 V power supply for modules LUL C08 is distributed via the bus and must be connected to the first TSX CANTDM4 junction box. The cable c.s.a. allows connection of up to 25 LUL C08 modules .

Above this number, another power supply must be connected to the next junction box.

A $\overline{\ldots}$ 24 V supply must be connected to module LUL C08 for outputs OA1, OA3 and LO1.

Information carried by the bus

Depends on the type of control unit used.

Control unit	Standard	Advanced	Multifunction
Starter status (ready, running, fault)			
Start and Stop commands			
Thermal overload alarm			
Remote reset via the bus			
Indication of motor load			
Fault signalling and differentiation			
Remote programming and monitoring of all functions			
"Log" function			
"Monitoring" function			
Alarms (overcurrent,)			
Functions performed			
For more detailed information, please refer to Use	r's Manual.		
Compatibility of CANopon com	nunicatio	n madula	ماغانه

Compatibility of CANopen communication module with control units

LUCA ••BL/B ••BL/C ••BL/D ••BL	All versions marketed after 2T04081 (1)
LUCM ••BL	All versions ≥ V3.2
LUCM T1BL	All versions ≥ V3.2

(1) This "date code" is made up as follows: 2T or 2C factory code.

04,05,06 and so on: year of manufacture. 08: week. 1: 1st day of the week.

References

TeSys motor starters - open version

TeSys U starter-controllers CANopen communication module and pre-wired coil connection components

LUB + LUL C08 + LU9B N11L



LU2B + LUL C08 + LU9M RL

Communication services

Communication module LUL C08 uses PDO, SDO and PKW type objects for data exchange (Process Data Objects, Service Data Objects, Periodically Kept in Acyclic Words).

Transmit an	d Receive PDO	
PDO 1	Real time command-control	Preconfigured and enabled
PDO 2, PDO 3	Unused	To be defined by configuration
PDO 4	Adjustment, diagnostics and acyclic exchanges	Preconfigured and enabled

References			
Description	Item	Reference	Weight kg
CANopen communication module	16	LUL C08	0.108
Note: The Electronic Data Sheets (EDS), ar "www.schneider-electric.com".	nd user's manual	s are available on the	website

Pre-wired components simplify wiring and reduce wiring errors.

Connection of communication module output terminals to the coil terminals

By pre-wired connector or wire link.

Pre-wired connector: pre-wired coil connection

The use of a power base without pre-wired control circuit connections is recommended.

Description	For use with power base	Item	Reference	Weight kg
Pre-wired coil connection	LUB ●●	17	LU9B N11L	0.050
	LU2B ●●	18	LU9M RL	0.450

Wire link:

Allows insertion, for example, of an emergency stop control or a voltage interface. This type of connection must be used for a reversing starter-controller assembled using an LU6M reverser block for separate mounting. When reverser block LU6M and the power base are mounted side-by-side, a pre-wired coil connection LU9M RL may be used.

Description	Length	Item	Reference	Weight
	m			kg
Standard				
Cables equipped with	0.3	14	TSX CANCADD03	0.045
SUB-D connectors	1.0	14	TSX CANCADD1	0.065
	3	14	TSX CANCADD3	0.125
	5	14	TSX CANCADD5	1.500
Reel of cable	50	11	TSX CANCA50	_
	100	11	TSX CANCA100	-
UL approved				
Cables equipped with	0.3	14	TSX CANCBDD03	0.045
SUB-D connectors	1	14	TSX CANCBDD1	0.065
	3	14	TSX CANCBDD3	0.125
	5	14	TSX CANCBDD5	1.500
Reel of cable	50	11	TSX CANCB50	_
	100	11	TSX CANCB100	_

Separate components		
Description	Reference	Weight kg
Elbowed connector	TSX CANKCDF90T	-
Straight connector	TSX CANKCDF180T	_
Junction box	TSX CANTD M4	-

TeSys U starter-controllers DeviceNet communication module and pre-wired coil connection components



- 1 LED indicating module status
- 2 Fault signalling LED
- 3 LED indicating ---- 24 V supply ON for outputs OA1, OA3 and LO1 and 24 V bus
- 4 DeviceNet connector for bus link
- 5 == 24 V supply connection
- 6 Discrete input
- 7 Discrete input
- 8 Discrete output
- 9 Outputs for starter-controller commands (nonreversing and reversing)
- 10 Pin for connection to control unit (advanced or multifunction)

Presentation

When used in conjunction with the power base and control unit, communication module LUL C09 allows TeSys U starter-controllers and controllers to be controlled via DeviceNet.

Communication module LUL C09 is of the slave type and uses the TeSys U system's internal registers which can be accessed via DeviceNet.

Module LUL C09 has a configurable 24 V (0.5 A) discrete output and two configurable discrete inputs.

Connections

Serial bus topology



11 Industrial PLC: Industrial Programmable Controller equipped with a DeviceNet Master.

- 12 Connection and power distribution box for supply to DeviceNet communication modules.
- 13 Starter-controller.
- 14 DeviceNet communication module LUL C09.

Presentation (continued), references

TeSys motor starters - open version

TeSys U starter-controllers DeviceNet communication module and pre-wired coil connection components





Connection of power supplies

Information carried by the bus

Depends on the type of control unit used with module LUL C09.

Information accessible	LUL C09 in cor	njunction with:	
via DeviceNet	LUCA ••BL	LUCB/C/D ••BL	LUCM ••BL
	Standard control unit	Advanced control unit	Multifunction control unit
Starter status (ready, running, fault)			
Start and Stop commands			
Thermal overload alarm			
Remote reset via the bus			
Indication of motor load			
Fault signalling and differentiation			
Remote programming and monitoring of all functions			
"Log" function			
"Monitoring" function			
Alarms (overcurrent,)			

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Description	Item	Reference	Weight kg
DeviceNet communication module	14	LUL C09	0.108

Connection of communication module output terminals to the coil terminals

By pre-wired connector or wire link.

Pre-wired connector: pre-wired coil connection

The use of a power base without pre-wired control circuit connections is recommended.

Description	For use with power base	Reference	Weight kg
Pre-wired coil connection	LUB ●●	LU9B N11L	0.050
	LU2B ••••	LU9M RL	0.450

Wire link:

Allows insertion, for example, of an emergency Stop control or a voltage interface. This type of connection must be used for a reversing starter-controller assembled using an LU6M reverser block.

When this reverser block and the power base are mounted side-by-side, a pre-wired coil connection LU9M RL may be used.

Supply

The 24 V supply to DeviceNet LUL C09 modules is provided via the (V+ , V-) terminals.

The 24 V supply for the inputs/outputs must be provided separately from the supply to the LUL C09 modules.

The 24 V Aux terminal is for supply to the LUCM control unit or the LUTM controller.
TeSys U starter-controllers DeviceNet communication module and pre-wired coil connection components



Note: DeviceNet communication module LUL C09 is compatible with LUT M controllers.

TeSys U starter-controllers DeviceNet communication module and pre-wired coil connection components



Note: DeviceNet communication module LUL C09 is compatible with LUT M controllers.

TeSys U starter-controllers Advantys STB communication module and pre-wired coil connection components



- 1 Two-colour LED indicating module status
- 2 Fault signalling LED
- 3 LED indicating that == 24 V supply is ON
- 4 Bus connectors
- 5 == 24 V supply connection
- 6 Discrete input
- 7 Discrete input
- 8 Discrete output
- 9 Outputs for starter commands

Presentation

Communication module LUL C15 allows direct connection of TeSys U startercontrollers and controllers on an Advantys STB island, between two segments or at the end of a segment. In the latter case, the segment must be equipped with an EOS (End of segment) extension module STB XBE1100.

The starter-controller will then be able to make use of the services provided by Advantys STB: self-addressing, autobaud, fallback positions.

When used in conjunction with an LUC $\bullet \bullet \bullet BL$ or LUC $\bullet T1BL$ control unit, module LUL C15 provides control and command of the starter-controller and of the controller. For local control requirements, the module is equipped with a configurable, = 24 V, 0.5 A discrete output and two configurable discrete inputs.





- 10 Advantys STB island (NIM: Network Interface Module + I/O modules)
- 11 Extension module (EOS/End of segment) STB XBE1100.
- 12 Bus connecting cable LU9 RCD••, elbowed/straight, for connection of the first TeSys U communication module.
- 13 Starter-controller.
- 14 Communication module LUL C15.
- 15 Connector for connection of product either by wire link or using coil connection modules LU9 BN11L or LU9 MRL.
- 16 Line end adapter LU9 RFL15.
- 17 Bus connection cable LU9 RDDee, straight/straight, for connections between LUL C15 modules.
 18 Beginning of segment (BOS).

Connection of power supply for the outputs

A --- 24 V supply must be connected to module LUL C15 for outputs OA1, OA3 and LO1.

Information carried by the bus

Depends on the type of control unit used.

Depends on the type of control unit used.			
Control unit	Standard	Advanced	Multifunction
Starter status (ready, running, fault)			
Start and Stop commands			
Thermal overload alarm			
Remote reset via the bus			
Indication of motor load			
Fault signalling and differentiation			
Remote programming and monitoring of all functions			
"Log" function			
"Monitoring" function			
Alarms (overcurrent,)			
Functions performed			

For more detailed information, please refer to User's Manual.

Compatibility of Advantys STB communication module with control units

 LUCA ●●BL / B ●●BL / C ●●BL / D ●●BL
 All versions marketed after 2T04081 (1)

 LUCM ●●BL
 All versions ≥ V3.2

 LUCM T1BL
 All versions ≥ V3.2

(1) This "date code" is made up as follows: 2T or 2C: factory code. 04,05,06 and so on: year of

manufacture. 08: week. 1: 1st day of the week.

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Schneider Belectric

TeSys U starter-controllers Advantys STB communication module and pre-wired coil connection components

Possible architectures

The maximum number of starter-controllers and controllers that can be connected to an Advantys STB island depends on the Network Interface Module (NIM) used and the associated control units.

NIM		Number of starter-controllers			Number of controllers
(Network Inte Module)	erface	LUCA ••BL	LUCB ••BL LUCC ••BL LUCD ••BL	LUCM ••BL	LUCB •• LUCD •• LUCM ••
CANopen	Standard	17	17	15	15
	Basic	12	12	12	12
DeviceNet	Standard	18	18	16	16
	Basic	12	12	12	12
Profibus DP	Standard	9	8	8	8
	Basic	9	8	8	8
Interbus	Standard	2	2	1	1
	Basic	2	2	1	1
Fipio	Standard	4	4	4	4
Modbus plus	Standard	17	17	15	15
Ethernet	Standard	32	32	32	32

References			
Description	Item	Reference	Weight kg
Advantys STB communication module	14	LUL C15	0.108
Line end adapter	16	LU9 RFL15	0.012
End of segment (EOS)	11	STB XBE1100	_
Beginning of segment (BOS)	18	STB XBE1300	

Pre-wired components simplify wiring and reduce wiring errors.

Connection of communication module output terminals to the coil terminals

By pre-wired connector or wire link.

Pre-wired connector: pre-wired coil connection.

The use of a power base without pre-wired control circuit connections is recommended.

Description	For use with power base	Item	Reference	Weight kg
Pre-wired coil connection	LUB 🐽	19	LU9B N11L	0.050
	LU2B ●●	20	LU9M RL	0.450

Wire link:

Allows insertion, for example, of an emergency Stop control or a voltage interface. This type of connection must be used for a reversing starter-controller assembled using an LU6M reverser block for separate mounting. When reverser block LU6M and the power base are mounted side-by-side, a pre-wired coil connection LU9M RL may be used.

Cables				
Description	Length m	Item	Reference	Weight kg
Cables fitted with	0.3	12	LU9 RCD03	0.045
connectors, one straight and one elbowed	1	12	LU9 RCD10	0.065
	3	12	LU9 RCD30	0.125
	5	12	LU9 RCD50	1.500
Cables fitted with	0.3	17	LU9 RDD03	0.045
two straight connectors	1	17	LU9 RDD10	0.065
	3		LU9 RDD30	0.125

Note: User manuals are available on the website "www.schneider-electric.com".





TeSys U starter-controllers Modbus communication modules and pre-wired coil connection components



66970



- 1 Module status signalling LED
- 2 24 V supply connection
- 3 RJ45 connector for RS485 Modbus link
- 4 2 discrete inputs
- 5 1 discrete output
- 6 Outputs for starter commands

Presentation

Communication modules LUL C031 and LUL C033 enable the TeSys U startercontroller to be connected to the Modbus network.

They must have a = 24 V supply and must be used in conjunction with a = 24 V control unit, LUCe $\bullet \bullet BL$.

They incorporate a 0.5 A, = 24 V discrete output for local command requirements. The module LUL C033 also has two configurable discrete inputs.

Series type connection

Architecture



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11 12

- 7 Communication module LUL C031 or LUL C033
- 8 Pre-wired coil connection LU9B N11C
- 9 Connection cable VW3 A8 306 Ree with one RJ45 connector at each end
- 10 Modbus hub LU9 GC3 with channel connections to PLC and to starter-controller with RJ45 connectors
- 11 T-junction VW3 A8 306 TF ••
- 12 Line terminator VW3 A8 306 R

Information carried by the bus

Depends on the type of control unit used.

Standard	Advanced	Multifunction
		Value Provinced Image: Image

Functions performed

For more detailed information, please refer to User's Manual LU9 CD1, see page opposite.

Compatibility of Modbus communication modules

With starter-controllers and controllers		
Starter-controllers and controllers	LUL C031	LUL C033
LUB •• / LU2B•2		
LUT M ••BL		
Possible combinations		

Possible combinations.

References

TeSys motor starters - open version

TeSvs U starter-controllers Modbus communication modules and pre-wired coil connection components

Compatibility of Modbus communication modules (continued)

With power bases			
Control unit software versions		LUL C031	LUL C033
		V2.3 (1)	V2.2 (1)
LUCA ••BL	-	Yes	Yes
LUCB ••BL, LUCC ••BL and LUCD ••BL	-	Yes	Yes
LUCM ••BL	V1.04	Yes	No
	V1.05	Yes	Yes
	V1.06	Yes	No
	V1.10 <i>(1)</i>	Yes	Yes
With base controllers, version 1.200 (1)		
Control unit software versions		LUL C031	LUL C033
		V2.3 (1)	V2.1 (1)
LUCB TeeBL and LUCD TeeBL	-	No	Yes

LUB + LUL C03• + LU9B



LU2B + LUL C03e + LU9M

Description	Item	Reference	Weight kg	
Modbus communication modules	7	LUL C031	0.080	
	7	LUL C033	0.080	
Pre-wired components simplify wiring and reduce wiring errors				

V2.11 (1)

No

Yes

ed components simplify wiring and reduce wiring errors.

Connection of communication module output terminals to the coil terminals

By pre-wired connector or wire link.

Combinations not permitted.

Pre-wired connector: pre-wired coil connection

The use of a power base without pre-wired control circuit connections is recommended.

Description	For use with power base	Item	Reference	Weight kg
Pre-wired coil connection	LUB 🐽	8	LU9B N11C	0.045
	LU2B 🐽	13	LU9M RC	0.030

Wire link:

LUCM TeeBL

(1) And higher versions

References

Allows insertion, for example, of an emergency Stop control or a voltage interface. This type of connection must be used for a reversing starter-controller assembled using an LU6M reverser block for separate mounting. When reverser block LU6M and the power base are mounted side-by-side, a pre-wired coil connection LU9M RC may be used.

Connection of communication modules on the serial bus

Achieved either by means of a Modbus hub or using T-junctions.

•		• •		
Description	Length m	ltem	Reference	Weight kg
Modbus hub 8 slaves	-	10	LU9 GC3	0.260
Cables fitted with	0.3	9	VW3 A8 306 R03	0.045
2 x RJ45 connectors	1	9	VW3 A8 306 R10	0.065
	3	9	VW3 A8 306 R30	0.125
T-junctions (1)	0.3	11	VW3 A8 306 TF03	0.032
	1	11	VW3 A8 306 TF10	0.032
RS 485 line terminator	_	12	VW3 A8 306 R	0.012

TeSvs U user's manual (2)

Application	Language	Reference	Weight kg
On CD-Rom	Multi-language (3)	LU9 CD1	0.022

(1) Fitted with 2 x RJ45 female connectors (bus side) and a 0.3 m or 1 m length cable supplied with an RJ45 male connector (station side).

(2) The CD-Rom contains user's manuals for the AS-Interface and Modbus communication modules, multifunction control units and gateway modules, as well as the gateway programming software

(3) English, French, German, Italian, Spanish

Communication gateways LUF P

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Presentation

Communication gateways LUF P allow connection between the Modbus serial link and Fipio, Profibus DP or DeviceNet field buses.

After configuration, these gateways manage information which can be accessed by the Modbus serial link and make this information available for read/write functions (command, monitoring, configuration and adjustment) on the field buses.

An LUF P communication gateway consists of a box which can be clipped onto a 35 mm omega rail, allowing connection of up to 8 Slaves connected on the Modbus serial link.

Example of architecture



Description

Front panel of the product

- 1 LED indicating :
 - communication status of the Modbus serial links,
 - gateway status,
- communication status of the Fipio, Profibus DP or DeviceNet bus.
- 2 Connectors for connection to Fipio, Profibus DP or DeviceNet buses.

Underside of product

- 3 RJ45 connector for connection of the Modbus serial link
- 4 RJ45 connector for link to a PC
- 5 == 24 V power supply

Software set-up

For the Fipio bus, software set-up of the gateway is performed using either PL7 Micro/Junior/Pro software or ABC Configurator software. For the Profibus DP and DeviceNet buses, software set-up is performed using ABC Configurator. This software is included in the TeSys U user's manual.

(1) Connection kit for PowerSuite software workshop (see page 1/74).

Characte page 1/9	eristics, references: 95	Dimensions: page 1/95	Schemes: page 1/118	
1/94			Schneider GElectric	



Characteristics, references, dimensions

TeSys motor starters - open version Communication gateways LUF P

Bus type			Fipio		Profibus DP	DeviceNet	
Invironment	Conforming to IEC 60664		Degree of pollution	n: 2			
mbient air temperature	Around the device	°C	+ 5+ 50				
egree of protection			IP 20			-	
lectromagnetic	Emission		Conforming to IE	C 50081-2	: 1993		
ompatibility	Immunity		Conforming to IE	C 61000-6	-2: 1999		
lumber of Modbus slaves v	which can be connected		≤8				
onnection	Modbus		By RJ45 connect	or conform	ning to Schneider Electric RS4	85 standard	
	To a PC				werSuite connection kit		
	Field bus		By SUB D9 femal connector	е	By SUB D9 female connector	By 5-way removabl screw connector	е
upply		v	External supply, $= 24 \pm 10 \%$				
onsumption	Max.	mA	280				
	Typical	mA	100				
ndication/diagnostics			By LED on front p	anel			
ervices	Profile		FED C32 or FED		_	_	
	Command		26 configurable w		122 configurable words	256 configurable w	ords
	Monitoring		26 configurable w	. ,	122 configurable words	256 configurable words	
	Configuration and adjustment		By gateway mini i	. ,	· · · ·		
References							
	Description	For use with			With bus/ serial link	Reference	Weight
	Communication	TeSys I	U starter-controller	S,	Fipio/Modbus	LUF P1	0.24
	gateways	Altistar			Profibus DP/Modbus	LUF P7	0.24
		Altivar 3 Altivar 3	,		DeviceNet/Modbus	LUF P9	0.24
Connection accessorie	S						
4	Description	For use	e with	Length m	Connectors	Reference	Weight kg
	Connection cables	Modbus	S	3	1 RJ45 type connector and one end with stripped wires	VW3 A8 306 D30	0.15
TSX FP ACC 12					2 RJ45 type connectors	VW3 A8 306 R03	0.05
					2 RJ45 type connectors	VW3 A8 306 R10	0.05
0				3	2 RJ45 type connectors	VW3 A8 306 R30	0.15
	Connectors	Fipio		-	1 SUB-D 9 male connector	TSX FP ACC12	0.04
Law .			s mid line	_	1 SUB-D 9 male connector	490 NAD 911 04	
490 NAD 911 03		Profibu	s line end	-	1 SUB-D 9 male connector	490 NAD 911 03	
Documentation							
	Description	Mediur	n Language			Reference	Weight kg
	User's manual for TeSys U range <i>(2)</i>	CD-Roi	m Multilingua Spanish	l: English,	French, German, Italian,	LU9 CD1	0.02
Dimensions							
		_					





(1) If the gateway is configured using PL7 and not ABC Configurator, the I/O capacity is limited to a total of 26 words.

(2) This CD-Rom contains user's manuals for AS-Interface and Modbus communication modules, multifunction control units and gateways, as well as for the gateway programming software, ABC Configurator.

Presentation, description: Setting-up: page 1/94 page 1/94		Schemes: page 1/118		
		Schneider Gelectric		1/95

Environment			
Product certifications			UL, CSA, CCC, GOST, ASEFA.
			ABS, BV, DNV, GL, LROS.
			ATEX.
Conforming to standards			IEC/EN 60947-6-2, CSA C22-2 N°14, Type E
			UL 508 type E: with phase barrier LU9 SP0
Rated insulation voltage (Ui)	Conforming to IEC/EN 60947-1, overvoltage category III,	v	690
	degree of pollution: 3		
	Conforming to UL508,	V	600
	CSA C22-2 n°14		
Rated impulse	Conforming to	kV	6
vithstand voltage (Uimp)	IEC/EN 60947-6-2 Conforming to IEC/EN 60947-1	V	Detuces the control or conflictly size it and the main size it. 400
Safety separation of circuits	appendix N	v	Between the control or auxiliary circuit and the main circuit: 400
			Between the control and auxiliary circuits: 400
Degree of protection	Front panel outside connection		IP 40
Conforming to IEC/EN 60947-1	zone		
protection against	Front panel and wired terminals		IP 20
lirect finger contact)	Other faces		IP 20
			(1994) AN
Protective treatment	Conforming to IEC/EN 60068	<u> </u>	"TH"
	Conforming to IEC/EN 60068-2-30	Cycles	
	Conforming to IEC/EN 60068-2-11	h ℃	48 -40+ 85
mbient air temperature round the device	Storage	ິ ເ	- 40+ 85 Power bases and standard and advanced control units: - 25+ 70.
	Operation	ι.	(At temperatures above 60°C and up to 70°C, for starter-controller LUB32, leave a
			minimum gap of 9 mm between products).
			Power bases and multifunction control units: - 25+ 60.
			(At temperatures above 45 °C, leave a minimum gap of 9 mm between products.
			At temperatures above 55 °C and up to 60 °C, leave a gap of 20 mm between products.)
Aximum operating altitude		m	2000
aximum operating attraute			2000
Operating positions	In relation to normal vertical mounting plane		
lame resistance	Conforming to LIL 04		V2
ומווופ ובסוסנמוונפ	Conforming to UL 94 Conforming to	°C	960 (parts supporting live components)
	IEC/EN 60695-2-12	°C	650 (parts supporting live components)
		J	
invironmental restrictions			Cadmium and silicone-free, recyclable
Shock resistance	Conforming to IEC/EN60068-2-27		Power poles open: 10 gn
/2 sine wave = 11 ms	(1)		Power poles closed: 15 gn
	Conforming to IEC/EN 60068-2-6		
			Power poles open: 2 gn
300 Hz	(1)		Power poles closed: 4 gn (2)
i300 Hz Resistance to	(1)	kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3
300 Hz Resistance to lectrostatic discharge	(1) Conforming to IEC/EN 61000-4-2	kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4
300 Hz Resistance to lectrostatic discharge mmunity to radiated high- requency disturbance	(1)	kV V/m	Power poles closed: 4 gn (2) In open air: 8 - Level 3
300 Hz Resistance to lectrostatic discharge mmunity to radiated high- requency disturbance mmunity to fast	(1) Conforming to IEC/EN 61000-4-2	kV V/m kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4 10 - Level 3 All circuits except for serial link: 4 - Level 4
300 Hz Resistance to lectrostatic discharge mmunity to radiated high- requency disturbance mmunity to fast	(1) Conforming to IEC/EN 61000-4-2 Conforming to IEC/EN 61000-4-3 Conforming to IEC/EN 61000-4-4	kV V/m	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4 10 - Level 3
300 Hz Resistance to lectrostatic discharge mmunity to radiated high- requency disturbance mmunity to fast ransient currents mmunity to dissipated	(1) Conforming to IEC/EN 61000-4-2 Conforming to IEC/EN 61000-4-3	kV V/m kV kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4 10 - Level 3 All circuits except for serial link: 4 - Level 4 Serial link: 2 - Level 3 Common mode Serial mode
300 Hz Resistance to lectrostatic discharge mmunity to radiated high- requency disturbance mmunity to fast ransient currents mmunity to dissipated	(1) Conforming to IEC/EN 61000-4-2 Conforming to IEC/EN 61000-4-3 Conforming to IEC/EN 61000-4-4 Conforming to IEC/EN 60947-6-2 Uc ~ 24240 V,	kV V/m kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4 10 - Level 3 All circuits except for serial link: 4 - Level 4 Serial link: 2 - Level 3
300 Hz Resistance to lectrostatic discharge mmunity to radiated high- requency disturbance mmunity to fast ransient currents mmunity to dissipated	(1) Conforming to IEC/EN 61000-4-2 Conforming to IEC/EN 61000-4-3 Conforming to IEC/EN 61000-4-4 Conforming to IEC/EN 60947-6-2 Uc ~ 24240 V, Uc $= 48220$ V	kV V/m kV kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4 10 - Level 3 All circuits except for serial link: 4 - Level 4 Serial link: 2 - Level 3 Common mode Serial mode 2 1
300 Hz Resistance to dectrostatic discharge mmunity to radiated high- requency disturbance mmunity to fast ransient currents mmunity to dissipated shock waves	(1) Conforming to IEC/EN 61000-4-2 Conforming to IEC/EN 61000-4-3 Conforming to IEC/EN 61000-4-4 Conforming to IEC/EN 60947-6-2 Uc $\sim 24240 \text{ V},$ Uc $= 24 \text{ V} = 24 \text{ V}$	kV V/m kV kV kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4 10 - Level 3 All circuits except for serial link: 4 - Level 4 Serial link: 2 - Level 3 Common mode Serial mode 2 1 Not applicable
/ibration resistance 5300 Hz Resistance to electrostatic discharge mmunity to radiated high- requency disturbance mmunity to fast ransient currents mmunity to dissipated shock waves mmunity to conducted high-frequency disturbance	(1) Conforming to IEC/EN 61000-4-2 Conforming to IEC/EN 61000-4-3 Conforming to IEC/EN 61000-4-4 Conforming to IEC/EN 60947-6-2 Uc ~ 24240 V, Uc $= 48220$ V	kV V/m kV kV	Power poles closed: 4 gn (2) In open air: 8 - Level 3 On contact: 8 - Level 4 10 - Level 3 All circuits except for serial link: 4 - Level 4 Serial link: 2 - Level 3 Common mode Serial mode 2 1

Without modifying the contact states, in the most unfavourable direction.
 2 gn with Advantys STB or CANopen communication modules.

Refere	nces :	Dimensions :	Schemes :
pages	1/62 to 1/71	pages 1/110 and 1/111	pages 1/112 to 1/119
1/96		Schneid	er

Characteristics

TeSys motor starters - open version TeSys U starter-controllers Power bases and control units

Power base, control unit of	r reverser block type		LUB 12 + LUCA or LUCB or LUCC or LUCD	LUB 32 + LUCA or LUCB or LUCC or LUCD	LUB 12 + LUCM	LUB 32 + LUCM	LU2M LU6M
Power circuit conn	ection characteristics						
Connection to Ø 4 mm	screw clamp terminals						
Flexible cable	1 conductor	mm ²	2.510	2.510	2.510	2.510	2.510
without cable end	2 conductors	mm ²	1.56	1.56	1.56	1.56	1.56
Flexible cable	1 conductor	mm ²	16	16	16	16	16
with cable end	2 conductors	mm ²	16	16	16	16	16
Solid cable	1 conductor	mm ²	110	110	110	110	110
without cable end	2 conductors	mm ²	16	16	16	16	16
Screwdriver	2 001000013		Philips n° 2 or flat sc		10	10	10
Fightening torque		N.m	1.92.5	1.92.5	1.92.5	1.92.5	1.92.5
		N.m	1.92.5	1.92.5	1.92.5	1.92.5	1.92.5
Control circuit con	nection characteristics						
Connection to Ø 3 mm	screw clamp terminals						
lexible cable	1 conductor	mm²	0.751.5	0.751.5	0.751.5	0.751.5	0.751.
without cable end	2 conductors	mm ²	0.751.5	0.751.5	0.751.5	0.751.5	0.751.
lexible cable	1 conductor	mm ²	0.341.5	0.341.5	0.341.5	0.341.5	0.341.
with cable end	2 conductors	mm ²	0.341.5	0.341.5	0.341.5	0.341.5	0.341.
Solid cable	1 conductor	mm ²	0.751.5	0.751.5	0.751.5	0.751.5	0.751.
without cable end	2 conductors	mm ²	0.751.5	0.751.5	0.751.5	0.751.5	0.751.
		nin-			0.751.5	0.751.5	0.751.
Screwdriver		N	Philips n° 1 or flat sc		0.0.10		0.0 1.5
Fightening torque		N.m	0.81.2	0.81.2	0.81.2	0.81.2	0.81.2
Control circuit cha	racteristics						
Rated voltage	\sim 50/60 Hz	v	24240	24240	-	-	-
of control circuit	=	v	24220	24220	24	24	-
/oltage limits	24 V (1)	v	2027	2027	2028	2028	-
Operation	~24 V	v	2026.5	2026.5	_	_	_
Operation	\sim or $=$ 4872 V	v	\sim 38.572. == 38.5		-	-	_
		V			-	-	
	~ 110240 V	-	~ 88264	~ 88264	-	-	-
	110220 V	V	88242	88242	-	-	-
Drop-out	24 V	v	14.5	14.5	14.5	14.5	-
	\sim 24 V	v	14.5	14.5	-	-	-
	\sim or == 4872 V	v	29	29	-	-	-
	∼ 110…240 V, == 110…220 V	V	55	55	-	-	-
Typical consumption	24 V	mA	130	220	150	200	120
I max while closing	\sim 24 V	mA	140	220	-	-	2360
6	~ or == 4872 V	mA	280	280	-	_	2300
	~ 110240 V, == 110220 V	mA	280	280	_	_	1000
I rms sealed	== 24 V	mA	60	80	70	75	120
TTTIS Sealed	\sim 24 V	mA	70	90	-	-	
							(2)
	\sim or $=$ 4872 V	mA	35	45	-	-	(2)
	∼ 110240 V, 110220 V	mA	35	25	-	-	(2)
leat dissipation		w	2	3	1.7	1.8	-
Operating time	Closing	ms	24 V: 70; 48 V: 60; ≥	72 V: 50	75	65	-
	Opening	ms	35	35	35	35	-
Resistance to micro-breaks	i	ms	3	3	3	3	-
Resistance to voltage dips	IEC/EN 61000-4-11		At least 70 % of Uc for	or 500 ms			-
Mechanical durability	In millions of operating cycles		15	15	15	15	_
Maximum operating rate	In operating cycles per hour		3600	3600	3600	3600	_
· •	1 0 7 1		5000				
Main pole characte			1.	1.			
lumber of poles			3	3	3	3	-
solation	Possible		Yes	Yes	Yes	Yes	-
conforming to IEC/EN 60947-1	Padlocking		1 padlock with Ø 6.9	mm shank			-
Rated thermal current		Α	12	32	12	32	-
Rated operational current	To IEC/ Category AC-41		θ≤70°C: 12A	θ≤70°C: 32A	θ ≤ 55°C: 12A	θ ≤ 55°C: 32A	-
Ue≤440V)	EN 60947-6-2 Category AC-43		θ ≤ 70°C: 12A	θ≤70°C: 32A	θ ≤ 55°C: 12A	θ≤55°C:32A	-
Rated operational voltage		v	690 (3)	690 (3)	690 <i>(3)</i>	690 <i>(3)</i>	-
requency limits	Of the operating current	Hz	4060	4060	4060	4060	_
Power dissipated	Operational current	A	3 6 9 12		1000	1000	
ower dissipated n the power circuits	•						-
	Power dissipated in all three poles	w	0.1 0.3 0.6 1.1	2.4 4.6 7.5			-
·			000 440	500 690			
	abort airauit						-
	short-circuit	V	230 440				
Rated breaking capacity on	short-circuit	kA	50 50	10 4			-
Rated breaking capacity on Fotal breaking time Fhermal limit	short-circuit With Isc max on 440 V				90	120	- -

(2) No consumption sealed. (3) For 690 V, use phase barrier LU9 SP0.

1

Reversing power bases and auxiliary contacts

Duration of inrush phase		\sim 50/60 Hz	ms	25		
-		=	ms	15		
Maximum	Without change of direction	1	ms	75		
operating time	With change of direction		ms	150		
General chara	cteristics of auxilia	ry contact	S			
Conventional thermal current (Ith)	For ambient temperature θ	< 70 °C	A	5		
Frequency of the ope	erational current		Hz	Up to 400		
Minimum switching o	capacityλ = 10 ⁻⁸	U min	٧	17		
		l min	mA	5		
Short-circuit protection	Conforming to IEC/EN 609	47-5-1	A	gG fuse: 4		
Short-time rating	Permissible for	1 s	Α	30		
		500 ms	Α	40		
			Α	50		
Insulation resistance	•		$\mathbf{m}\Omega$	10		
Non-overlap time	Guaranteed between N/C and N/O contacts		ms	2 (on energisation and on de-energisation)		
Specific chara	cteristics of auxilia	ry contact	ts bu	ilt-into the power base		
Linked contacts	Conforming to IEC/EN 609	47-4-1		Each power base has 1 N/O contact and 1 N/C contact which are mechanically linked		
Mirror contact	Conforming to IEC/EN 609	47-1		The N/C contact fitted in each power base reliably represents the state of the power contacts (safety scheme)		
Rated operational vo	Itage (Ue)		٧	Up to \sim 690; $=$ 250		
Rated insulation	Conforming to IEC/EN 609	47-5-1	۷	690		
voltage (Ui)	Conforming to UL, CSA		v	600		
Specific chara	cteristics of auxilia	ry contact	ts in	modules LUF N, of auxiliary contacts LUA1		
and of reverse	r blocks LU2M and	LU6M				
Rated operational vo	Itage (Ue)		v	Up to \sim 250; == 250		
Rated insulation	Conforming to IEC/EN6094	7-5-1	v	250		
voltage (Ui)	ge (Ui) Conforming to UL, CSA		v	250		

Rated operational power of contacts Conforming to IEC/EN 60947-5-1

a.c. supply, categories AC-14 and AC-15 Electrical durability (valid for up to 3600 operating cycles/hour) on an inductive load such as the coil of an electromagnet: making current $(\cos \varphi 0.7) = 10$ times the power broken $(\cos \varphi = 0.4)$

d.c. supply,	category	DC-13
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Electrical durability (valid for up to 1200 operating cycles/hour) on an inductive load such as the coil of an electromagnet, without economy resistor, the time constant increasing with the load.

	V	24	48	115	230	400	440	600
1 million operating cycles	VA	60	120	280	560	960	1050	1440
3 million operating cycles	VA	16	32	80	160	280	300	420
10 million operating cycles	VA	4	8	20	40	70	80	100



125 250 V 24 48 w 120 90 75 68 w 70 50 38 33 w 25 12 18 14



References : pages 1/63 and 1/64

Dimensions : pages 1/110 and 1/111

Schemes pages 1/112 to 1/119

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Schneider Blectric

			ontrol units L	UCA							
Protection	Motor ty				3-phase						
		ning to standard			IEC/EN 60947-	6-2, UL 50	08, CSA C22-2	2 n°14			
Overload protection		class conforming t			10						
protection		508, IEC/EN 60947-6-2			4060						
		ature compensation		Hz °C							
				С.	- 25+ 70						
Short-circuit		on against phase ir threshold	Indalance		Yes 14.2 x Ir (settin	a ourropt)					
protection		tolerance			± 20 %	g current)					
•	mpping	tolerance			120 /0						
Characteris	tics of	advanced c	ontrol units	LUCB	. LUCC an	d LUCE	כ				
Control unit type					LUCB				LUCD		
Protection	Motor ty	pe		1	3-phase		Single-pl	nase	3-phase		
		ning to standard			IEC/EN 60947-	6-2, UL 50		0947-6-2, UL 508		47-6-2, UL 508	
		0			CSA C22-2 n°1	4	CSA C22	-2 n°14	CSA C22-2	n°14	
Overload		class conforming t			10		10		20		
protection		IEC/EN 60947-6-2									
		icy limits of the ope		Hz	4060		4060		4060		
		ature compensation		°C	- 25+ 70		- 25+ 5	5	- 25+ 70		
		on against phase ir	nbalance		Yes		-		Yes		
Short-circuit protection		threshold			14.2 x lr max.		14.2 x lr i	nax.	14.2 x lr ma:	Χ.	
protection	Iripping	tolerance			± 20 %		± 20 %		± 20 %		
Characteria	tice of	multifunatio	on control un	ite L L	ICM						
			on control un								
Protection	Motor ty				Parameters ca		<u> </u>	r 3-phase			
		ning to standard			IEC/EN 60947-	,					
Overload protection		class conforming t			5, 10, 15, 20, 25, 30 (selectable)						
protection		UL 508, IEC/EN 60947-6-2			50 60						
	Frequency limits of the operational current Temperature compensation			Hz °C	5060 - 25+ 55						
Communication					- 25+ 35 RS 485 multi-drop						
interface for		Physical interface Connections			RJ45 on front panel						
erminal on	Protocol				Modbus RTU	anei					
enclosure door		m transmission spe	hae	bit/s							
		m return time		ms	200						
Display	Туре				LCD, 2 lines of 12 characters						
		ge version			Multilanguage (English, French, German, Italian, Spanish)						
	Precisio				±5%	<u>(</u>	,	,,,	,		
	Resolut				1 % of Ir						
Auxiliary supply	Externa			v	24, with max	imum ripp	ole of ± 10 %.				
	Heat dis			W 0.8							
	on tab	le for protect	tion devices	and a	larms on n	nultifui	nction co	ntrol units l	LUCM		
Configuration	Tripping		Alarm		stment of tripping		Adjustment of time before		Adjustment o	alarm	
Configuration		Tripping	Alami						three held		
Configurati				thresh	nold	- 1	tripping	1 C	threshold		
Configuration		Tripping Factory setting	Factory setting		nold	- 1	tripping Range	Default value		Default value	
		Factory setting		thresh Range	old Defau	- 1		Default value			
Overcurrent		Factory setting Activated (1)	Factory setting	thresh Range 3171	nold Defau r 14.2	It value	Range	<u> </u>	Range	_	
Overcurrent		Factory setting Activated (1)		thresh Range	nold Defau r 14.2	It value		5			
Overcurrent Overload		Factory setting Activated (1) Activated (1)	Factory setting – Activated	thresh Range 317 I 0.532	r 14.2 2 A (2) Ir min	It value	Range	_ 5	Range - 10100 % of the thermal state	 85 %	
Overcurrent Overload Earth fault		Factory setting Activated (1) Activated (1) Activated	Factory setting	thresh Range 3171	Defau r 14.2 2A (2) Ir min Ir min 0.3 Ir min	It value	Range	5 0.1 s	Range – 10100 % of	_ 85 %	
Overcurrent Overload Earth fault Phase imbalance		Factory setting Activated (1) Activated (1) Activated Activated	Factory setting - Activated Activated	thresh Range 317 I 0.532 0.25	Defau r 14.2 2A (2) Ir min Ir min 0.3 Ir min	It value	Range Class: 530	- 5 0.1 s 5 s	Range - 10100 % of the thermal state 0.25 Ir min	– 85 % 0.3 lr min	
Overcurrent Overload Earth fault Phase imbalance Torque limitation		Factory setting Activated (1) Activated (1) Activated Activated Deactivated	Factory setting - Activated Activated Activated	thresh Range 317 I 0.532 0.25 1030	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir	in 0 1	Range Class: 530 0.11.2 s 0.220 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 %	- 85 % 0.3 Ir min 10 %	
Overcurrent Overload Earth fault Phase imbalance Torque limitation No-load running		Factory setting Activated (1) Activated (1) Activated Activated Deactivated Deactivated	Factory setting Activated Activated Activated Deactivated	threst Range 317 I 0.532 0.25 1030 18 Ir	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir	in 0 1 1 1	Range Class: 530 0.11.2 s 0.220 s 30 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir	- 85 % 0.3 lr min 10 % 2 lr	
Overcurrent Overload Earth fault Phase imbalance Forque limitation No-load running Long starting time	e	Factory setting Activated (1) Activated (1) Activated Activated Deactivated Deactivated Deactivated	Factory setting - Activated Activated Deactivated Deactivated Deactivated Deactivated	thresh Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir Ir Ir 0.5 Ir Ir Ir	in 0 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir	- 85 % 0.3 lr min 10 % 2 lr 0.5 lr	
Overcurrent Overload Earth fault Phase imbalance Forque limitation No-load running Long starting time	e	Factory setting Activated (1) Activated (1) Activated Activated Deactivated Deactivated Deactivated Deactivated dditional fur	Factory setting - Activated Activated Ceactivated Deactivated Deactivated Deactivated Ceactivated Ceactivated	thresh Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir Ir Ir 0.5 Ir Ir Ir	in 0 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir	- 85 % 0.3 lr min 10 % 2 lr 0.5 lr	
Overcurrent Overload Earth fault Phase imbalance Torque limitation No-load running Long starting time Configurati	e	Factory setting Activated (1) Activated (1) Activated Deactivated Deactivated Deactivated Deactivated dditional fur Factory setting	Factory setting - Activated Activated Activated Deactivated Deactivated Deactivated Ctions on m Setting range	thresh Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir ultifu	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir min Ir min 0.3 Ir min % 10 % 2 Ir Ir Ir 0.5 Ir Ir Ir	in 0 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir		
Overcurrent Overload Earth fault Phase imbalance Torque limitation No-load running Long starting time Configurati Reset	e on of a	Factory setting Activated (1) Activated (1) Activated Deactivated Deactivated Deactivated Deactivated dditional fun Factory setting Manual	Factory setting - Activated Activated Activated Deactivated Deactivated Deactivated Ctions on m Setting range Manual, automatic	thresh Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir ultifu	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir min Ir min 0.3 Ir min % 10 % 2 Ir Ir Ir 0.5 Ir Ir Ir	in 0 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir	- 85 % 0.3 lr min 10 % 2 lr 0.5 lr	
Overcurrent Overload Earth fault Phase imbalance Torque limitation No-load running Long starting time Configurati Reset Time before reset	e on of a	Factory setting Activated (1) Activated (1) Activated Deactivated Deactivated Deactivated Deactivated dditional fur Factory setting Manual 120 s	Factory setting - Activated Activated Deactivated Deactivated Deactivated Deactivated Ctions on m Setting range Manual, automatic 11000 s	threst Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir ultifu or remo	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir Ir Ir 0.5 Ir Ir Ir nction con te	in 0 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir	- 85 % 0.3 lr min 10 % 2 lr 0.5 lr	
Overcurrent Overload Earth fault Phase imbalance Torque limitation No-load running Long starting time Configurati Reset Time before reset	e on of a	Factory setting Activated (1) Activated (1) Activated Deactivated Deactivated Deactivated Deactivated dditional fun Factory setting Manual 120 s 3-phase motor	Factory setting - Activated Activated Activated Deactivated Deactivated Deactivated Ceactivated Ceacti	threst Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir ultifu or remo	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir Ir Ir 0.5 Ir Ir Ir nction con te	in 0 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir	- 85 % 0.3 lr min 10 % 2 lr 0.5 lr	
Overcurrent Overload Earth fault Phase imbalance Torque limitation No-load running Long starting time Configuration Reset Time before reset Type of load	e on of a	Factory setting Activated (1) Activated (1) Activated Deactivated Deactivated Deactivated dditional fun Factory setting Manual 120 s 3-phase motor Self-cooled	Factory setting - Activated Activated Activated Deactivated Deactivated Deactivated Ctions on m Setting range Manual, automatic 11000 s 3-phase motor, sin Self-cooled, force	threst Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir ultifu or remo	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir Ir Ir 0.5 Ir Ir Ir se motor Ir	in 0 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s		Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir	- 85 % 0.3 lr min 10 % 2 lr 0.5 lr	
Overcurrent Overload Earth fault Phase imbalance Torque limitation No-load running Long starting time	e on of a	Factory setting Activated (1) Activated (1) Activated Deactivated Deactivated Deactivated Deactivated dditional fur Factory setting Manual 120 s 3-phase motor Self-cooled English	Factory setting - Activated Activated Activated Deactivated Deactivated Deactivated Ceactivated Ceacti	threst Range 317 I 0.532 0.25 1030 18 Ir 0.31 18 Ir ultifu or remo gle-phas cooled erman, I	nold Defau r 14.2 2 A (2) Ir min Ir min 0.3 Ir m % 10 % 2 Ir Ir Ir 0.5 Ir Ir 0.5 Ir Ir se motor	in 0 0 1 1 1 1 1 1 1 1 1	Range Class: 530 11.2 s 1.220 s 30 s 200 s 200 s lits LUCN	- 5 0.1 s 5 s 5 s 10 s 10 s	Range - 10100 % of the thermal state 0.25 Ir min 1030 % 18 Ir 0.31 Ir 18 Ir	- 85 % 0.3 lr min 10 % 2 lr 0.5 lr lr	

References :	Dimensions :	Schemes :
pages 1/69 and 1/70	pages 1/110 and 1/111	pages 1/112 to 1/119

TeSys motor starters - open version TeSys U starter-controllers Limiter-disconnector, current limiter, thermal overload alarm function module and thermal overload fault signalling modules

Characteristics of limiter-	disconnector LU/	ALB1	
Rated insulation voltage (Ui)		v	690
conforming to standard IEC/EN 60947-1		-	
Conventional thermal current (Ith) conforming to standard IEC/EN 60947-1		A	32
Operating threshold	l rms	kA	50
Breaking capacity		V	440 690
		kA	130 70
Mounting			Directly on the upstream terminals of the starter-controller
Cabling			
Solid cable	1 conductor	mm²	1.510
	2 conductors	mm ²	1.56
Flexible cable without cable end	1 conductor	mm ²	110
	2 conductors	mm ²	16
Flexible cable with cable end	1 conductor	mm ²	16
	2 conductors	mm ²	16
Screwdriver			Phillips n°2 or flat screwdriver Ø 6 mm
Tightening torque		N.m	1.92.5
Characteristics of current	limiter LA9 LB92	0	
Rated insulation voltage (Ui)		v	690
conforming to standard IEC/EN 60947-1			
Conventional thermal current (Ith) conforming to standard IEC/EN 60947-1		A	63
Operating threshold	l rms	Α	1000
Breaking capacity		V	440 690
		kA	100 35
Mounting			Separate
Cabling			
Solid cable	1 conductor	mm ²	1.525
	2 conductors	mm ²	1.510
Flexible cable without cable end	1 conductor	mm ²	1.525
	2 conductors	mm ²	2.510
Flexible cable with cable end	1 conductor	mm ²	1.516
	2 conductors	mm ²	1.54
Screwdriver			Phillips n°2 or flat screwdriver Ø 6 mm
Tightening torque		N.m	2.2
Characteristics of thermal	overload alarm f	unctio	on modules LUF W10
Activation threshold			Fixed at 88% of the thermal tripping state
Hysteresis between activation and swi	itching off		5%
Display			By LED on front panel
Supply			Powered by the control unit
Discrete output characteristics	Туре		N/O contact
	AC-15		230 V max; 400 VA 100 000 operating cycles
	DC-13		24 V; 50 W 100 000 operating cycles
Conventional thermal current (Ith)	For ambient temperature θ < 70 °C	A	2
Short-circuit protection	Conforming to IEC/EN 60947-5-1	A	gG fuse: 2
Characteristics of thermal	overload fault si	gnalli	ng and reset modules
Module type			LUF DH11 LUF DA01 LUF DA10
Fault signalling			By LED on front panel
External power supply		v	~/
Module consumption		mA	7 at 24
•			1.1 at ~ 240
Discrete outputs	Туре		1 N/C+1 N/O 1 N/C 1 N/O
	AC-15		230 V max; 400 VA 100 000 operating cycles
	DC-13		24 V; 50 W 100 000 operating cycles
Conventional thermal current (Ith)	For ambient	A	2
	temperature θ < 70 °C	•	
Short-circuit protection	Conforming to IEC/EN 60947-5-1	A	gG fuse: 2
Reset input	Conductor c.s.a.	mm ²	0.2 min
	Length	m	500 (R = 50 Ω , L = 52.8 mH, Cp = 93 pF)
	~		

References :	Dimensions :	Schemes :	
pages 1/66 and 1/71	pages 1/110 and 1/111	pages 1/112 to 1/119	
1/100	s	Cchneider CElectric	

TeSys motor starters - open version TeSys U starter-controllers Function modules and communication modules

Analogue outpu	stics of motor loa			4 - 20 mA				
Signal delivered			_	Value of I average/Ir ratio within the range of 0 to 2 for LUCB and LUCD				
Signal delivered	1			Value of Laverage/Ir ratio within the ran	-			
Load impedance	6	Minimum	kΩ					
	-	Maximum	Ω	500				
		Typical	Ω	100				
Signal characte	ristics	Precision		±6%				
with advanced o								
Signal characte		Precision		± 10 %				
with multifuncti	on control unit	Resolution		1 % of Ir				
Supply				External 24 V				
Characteri	ctics of AS Inter		ation	modules ASILUF C5 and A				
	slics of AS-Intern	ace communic	cation					
Module type				ASILUF C5	ASILUF C51			
Product certific			_	AS-Interface V2.1 n° 52901	AS-Interface V2.1 n° 52303			
AS-Interface pro			*0	7.D.F.0	7.A.7.E			
Ambient air tem	perature		°C	Operation - 25+ 70 5	10			
Cycle time			ms	5 31 slaves				
Addressing	nnly		v	29.531.5	62 slaves			
AS-Interface su Current consum		On the	mA					
Current consum	iption	AS-Interface bus	mA	Normal operation: 25 Fault condition: 30				
		On 24 V supply	mA	200				
		for the outputs	V					
Auxiliary supply				24 ± 30 %				
Number of outp				2 dedicated to starter-controller coil ope				
	city of the solid state ou	tputs		0.5 A/24 V (outputs protected against s	short-circuits)			
Indication/diagr	nostics			By 2 LEDs on front panel				
Characteri	stics of Modbus	communicatio	n moo	ule LUL C03•				
Module type				LUL C031	LUL C033			
Physical interfa	ce			RS 485 multi-drop				
Connections				RJ45 on front panel				
Protocol				Modbus RTU				
Maximum trans	mission speed		bit/s	19 200 (self-configuration up to this val	ue)			
Maximum returr	n time		ms	30				
Addressing				By switches: from 031				
Ambient air tem	perature		°C	Operation - 25+ 55				
Discrete inputs		Number		-	2 (to be assigned according to the configuration)			
		Supply	v	-				
		Input current	mA	-	7			
	Nominal input values		v	== 24 (positive logic)				
		Current	mA	7				
	Response time	Change to state 1	ms	10 (± 30 %)				
		Change to state 0	ms	10 (± 30 %)				
	Input type			Resistive				
Solid state		Number		3, of which 2 dedicated to starter-control	oller coil operation			
Solid state		Supply	v	24				
Solid state outputs		Max. current	mA	500				
	Protection	gl fuse	Α	1				
	Protection Switching capacity		Α	1 0.5 A/24 V				

TeSys motor starters - open version TeSys U starter-controllers Function modules and communication modules

Communication	module			Profibus DP	CANopen	DeviceNet		
				LUL C07	LUL C08	LUL C09		
Services	Conformity class			NA	S 20 (Schneider Electric)	NA		
	Standard			Profibus DP	CIADS-301 V4.02 DR 303-2	IEC 62026-1, overvoltage category III degree of pollution: 3		
	Profile			LVSG V1.0 MS (Motor Starter) and MMS (Motor Management Starter)	-	ODVA (Open DeviceNe Vendor Association) MS (Motor Starter)		
	Protocol			Profibus DP	CAN 2.0A (2B passive)	CAN 2.0A (2B passive)		
	Address			1125	0127 (by switches)	063		
Structure	Physical interface			9-way SUB-D male	9-way SUB-D female	"Open Style" connector		
	Binary rate			9600 Kbits/s12 Mbits/s	10, 20, 50, 125, 250, 500 and 1000 Kbits/s (by switches)	125500 kbaud		
	Cables			2 shielded twisted pairs				
Supply for the	24 V		v	2028				
discrete outputs	Current consumption		Α	1.5 (max)				
and control	Protection by gl fuse		Α	2				
Ambient air tempe	erature		°C	Operation -25+55				
Logic inputs	Number		_	2 (to be assigned according	to the configuration)			
Logic inputs	· · ·				to the configuration)			
	Supply		V mA	7				
	Input current	Valtary	mA					
	Nominal input values	Voltage	V	24 (positive logic)				
		Current	mA	7				
	Response time	Change to state 1	ms	10 (± 30%)				
		Change to state 0	ms	10 (± 30%)				
	Input type		Resistive					
Discrete outputs	Number			3, of which 2 dedicated to starter-controller coil operation				
	Max. current		mA	500				
	Short-circuit protectior	 1		Yes				
	Switching capacity			0.5 A / 24 V				
Indication/diagno	stics			By 3 LEDs on front panel				
	tics of Advantys	s STB commur	vicatio	n module LUL C15				
Characteris			incatio					
)			CAN				
Physical interface	•							
Physical interface Connections				CAN	ive mode)			
Physical interface Connections Protocol			kbit/s	CAN Fire Wire CAN 2.0 and CAN 2.B (pass	ive mode)			
Physical interface Connections Protocol Transmission spe				CAN Fire Wire CAN 2.0 and CAN 2.B (pass	ive mode)			
Physical interface Connections Protocol Transmission spe Addressing				CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800	ive mode)			
Physical interface Connections Protocol Transmission spe Addressing Supply for the	eed 		kbit/s	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028	ive mode)			
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs	=== 24 V Current consumption		kbit/s V A	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max)	ive mode)			
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control	24 V Current consumption Protection by gl fuse		kbit/s	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028	ive mode)			
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	24 V Current consumption Protection by gl fuse		kbit/s V A A	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	eed 24 V Current consumption Protection by gl fuse erature		kbit/s V A A	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	eed 24 V Current consumption Protection by gl fuse erature Number		kbit/s V A A °C	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	eed 24 V Current consumption Protection by gl fuse erature Number Supply Input current	Voltage	kbit/s kbit/s V A A °C V	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	eed 24 V Current consumption Protection by gl fuse erature Number Supply	Voltage	kbit/s kbit/s V A A A °C V W MA	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	eed 24 V Current consumption Protection by gl fuse erature Number Supply Input current Nominal input values	Current	kbit/s kbit/s V A A A °C V mA V mA	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	eed 24 V Current consumption Protection by gl fuse erature Number Supply Input current	Current Change to state 1	kbit/s kbit/s V A A A °C V mA V mA ms	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7 10 (± 30 %)				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe	eed 24 V Current consumption Protection by gl fuse erature Number Supply Input current Nominal input values	Current	kbit/s kbit/s V A A A °C V mA V mA	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempo Discrete inputs	eed 	Current Change to state 1	kbit/s kbit/s V A A A °C V mA V mA ms	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7 10 (± 30 %) Resistive	to configuration)			
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempo Discrete inputs	eed 	Current Change to state 1	kbit/s kbit/s V A A A V V V W MA V MA MS MS	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7 10 (± 30 %) 10 (± 30 %) Resistive 3, of which 2 dedicated to sta				
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempo Discrete inputs	eed 	Current Change to state 1 Change to state 0	kbit/s kbit/s V A A A °C V mA V mA ms	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7 10 (± 30 %) 10 (± 30 %) Resistive 3, of which 2 dedicated to stat 500	to configuration)			
Physical interface Connections Protocol Transmission spe Addressing Supply for the	eed Trime 24 V Current consumption Protection by gl fuse Protection Protection Number Number Number Max. current Short-circuit protection	Current Change to state 1 Change to state 0	kbit/s kbit/s V A A A V V V W MA V MA MS MS	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7 10 (± 30 %) Resistive 3, of which 2 dedicated to sta 500 Yes	to configuration)			
Physical interface Connections Protocol Transmission spe Addressing Supply for the discrete outputs and control Ambient air tempe Discrete inputs	eed 24 V Current consumption Protection by gl fuse erature Number Supply Input current Nominal input values Response time Input type Number Max. current Short-circuit protectior Switching capacity	Current Change to state 1 Change to state 0	kbit/s kbit/s V A A A V V V W MA V MA MS MS	CAN Fire Wire CAN 2.0 and CAN 2.B (pass 800 Self-addressing 2028 1.5 (max) 2 Operation - 25+ 55 2 (to be assigned according 24 7 24 (positive logic) 7 10 (± 30 %) 10 (± 30 %) Resistive 3, of which 2 dedicated to stat 500	to configuration)			

TeSys motor starters - open version TeSys U starter-controllers Function modules and communication modules

Mandada ta su		eristics					
Module type		LUF W10, LUF V2 LUF DH11, LUF DA01 and		LUF V2	ASILUF C5 and ASI	LUF C51	
				LUF DA01 and LUF DA10		Inputs and 24 V auxiliary supply	Outputs
Connectors		Pitch		5.08	3.81	5.08	3.81
Flexible cable without cable end		1 conductor	mm²	0.21.5	0.141	0.21.5	0.141
		2 identical conductors	mm²	0.21	0.140.75	0.21	0.140.75
Flexible cable with cable end	Without insulated	1 conductor	mm²	0.251.5	0.251	0.251.5	0.251
	ferrule	2 identical conductors	mm²	0.251	0.250.34	0.251	0.250.34
	With insulated	1 conductor	mm²	0.251.5	0.250.5	0.251.5	0.250.5
	ferrule	2 identical conductors (Use a double cable end)	mm²	0.51	0.5	0.51	0.5
Solid cable without cable e	nd	1 conductor	mm²	0.21.5	0.141	0.21.5	0.141
		2 identical conductors mm ²		0.21	0.140.5	0.21	0.140.5
Conductor size 1 conductor		1 conductor		AWG 24 AWG 16	AWG 26 AWG 16	AWG 24 AWG 16	AWG 26 AWG 16
Tightening torq	ue		N.m	0.50.6	0.200.25	0.50.6	0.200.25
Flat screwdrive	r		mm	3.5	2.5	3.5	2.5
Module type	Module type			LUL C031,	LUFC 00	LUL C09	
				LUL C033, LUL C08 and LUL C15		Inputs and 24 V auxiliary supply	Connection on the bus
Connectors		Pitch		3.81	3.81	3.81	5 (Open Style) DeviceNet
Flexible cable without cable e	nd	1 conductor mm ²		0.141	0.141	0.141	0.22.5
		2 identical conductors mm ²		0.140.75	0.140.75	0.140.75	0.51.5
Flexible cable with cable end	Without insulated	1 conductor	mm²	0.251	0.251	0.251	0.252.5
	ferrule	2 identical conductors	mm²	0.250.34	0.250.34	0.250.34	0.251
	With insulated	1 conductor	mm²	0.250.5	0.250.5	0.250.5	0.252.5
	ferrule	2 identical conductors (Use a double cable end)	mm²	0.5	0.5	0.75	0.51.5
Solid cable without cable e	nd	1 conductor	mm²	0.141	0.141	0.141	0.22.5
		2 identical conductors	mm²	0.140.5	0.140.5	0.140.5	0.140.5
Conductor size		1 conductor		AWG 26 AWG 16	AWG 26 AWG 16	AWG 26 AWG 16	AWG 24 AWG 16
Tightening torq	ue		N.m	0.200.25	0.200.25	0.200.25	0.50.6
Flat screwdrive	-		mm	2.5	2.5	2.5	3.5





Tripping curves for control units LUCA, LUCB, LUCD



1 LUCD, 3 poles from cold state, class 20.

2 LUCA, LUCB, 3 poles from cold state, class 10.

3 LUCA, LUCB, LUCD, 3 poles from hot state.

Tripping curves for control units LUCC

Average operating times at 20 °C according to multiples of the setting current, tolerance : ± 20 %.



1 LUCC, single-phase, cold state.

2 LUCC, single-phase, hot state.



Time (s)

Tripping curves for control units LUCM

Cold state curves

Average operating times at 20 °C according to multiples of the setting current, tolerance : ± 20 %.



Tripping curves for control units LUCM

Hot state curves

Average operating times at 20 °C according to multiples of the setting current, tolerance : ± 20 %



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References : page 1/70

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1 Maximum peak current

2 32 A power base

3 12 A power base

Thermal limit on short-circuit U_ = 460 V



1 32 A power base

2 12 A power base



Use in category AC-41



Use in category AC-43 Ue ≤ 440 V









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Schneider Electric

Dimensions (continued), mounting

TeSys motor starters - open version TeSys U starter-controllers



(2) Retractable fixing lugs.

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Schneider



Multifunction control units LUCM

Control terminal block

LUCM	Multifunction Control Unit
24 V Aux + I) (4) (4) (4) (4) (4) (4) (4) (4) (4) (4

Basic scheme



- 1 and 2 Trips 3 and 4 Electromagnet
- 5 Power base rating 6 N/C
- 7 Earth
- 8 N/C
- 9 Earth
- 10 (lm/lr) 11 Rx/Tx
- 12 Vc1

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Alarm LUF W10

Function modules



Basic scheme



Indication of motor load

LUF V2 4-20 mA output

LUFV 2 Analogue output Module 24 V Aux 24 V Aux 4...20 mA F+ + NC L_ -0-

Basic scheme



100 Ω < load < 500 Ω = 30 V max and 40 mA min

Communication modules

Communication modules ASILUF C5 and ASILUF C51 Without pre-wired coil connection

ASILUF C5 or ASILUF C51	AS-Interface Module
	AS-i + _

With pre-wired coil connection LU9B N11C



With pre-wired coil connection LU9M RC

[
ASILUF C5 or ASILU	F C51	AS-Interface Module
	<u></u> 24 V	AS-i
LU9M RC Pre-wired coil	+ -	+ -

Basic scheme



Communication modules (continued) Modbus communication module LUL C031

Without pre-wired coil connection



Modbus communication module LUL C033 Without pre-wired coil connection

LUL C033				Mode	ous Module
o Com o OA1 o OA3	 	 24 V +	24 V Aux +	сом	(B) (F) > 0 (A) 0 (A)(A) (A) 0 (A) (

With pre-wired coil connection LU9B N11C

	L	
LUL C031	Modbus Mo	odule
LU9B N11C Pre-wired coil	5 6 + - + - 45	> 0 8

With pre-wired coil connection LU9B N11C

LUL C033					Mod	Ibus Module
LU9B N11C Pre-wired coil	PL01		24 V 	24 V Aux +	сом	(a) (e) (e) (a) (a) (b) (c) (c) (c) (c) (c) (c) (c) (c) (c) (c

With pre-wired coil connection LU9M RC

LUL C031			N	Iodbus Module
LU9M RC Pre-wired coil	b LO1	24 V	24 V Aux	(€) > 0 0 4 5 8

Basic scheme



With pre-wired coil connection LU9M RC

LUL C033					Мо	dbus Module
LU9M RC Pre-wired coil	6 L01	- E1	 24 V + 	24 V Aux +	сом	(a) (€) > 0 0 0 4 5 8



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Schneider Belectric

Communication modules (continued) Profibus DP communication module LUL C07 Without pre-wired coil connection



With pre-wired coil connection LU9B N11LC

LUL C07					Profit	ous DP Module
LU9B N11L Pre-wired coil	ф ГО1	o LI1	d LI2	 24 V		Bus

With pre-wired coil connection LU9M RC

LUL C07					Profil	ous DP Module
LU9M RL Pre-wired coil	ф Г01		+	<u> </u>		Bus

Basic scheme



DeviceNet communication module LUL C09 Without pre-wired coil connection



With pre-wired coil connection LU9B N11LC

LUL C09						DeviceNet Module
LU9B N11L Pre-wired coil	PL01	1	0 LI2	[+	== 24 V +	Bus

With pre-wired coil connection LU9M RL

LUL C09				DeviceNet Module
LU9M RL Pre-wired coil	0 L01	0 LI2 0 LI2	 24 V	

CANopen communication module LUL C08 Without pre-wired coil connection



With pre-wired coil connection LU9B N11LC

LUL C08			Ca	nopen Module
LU9B N11L Pre-wired coil	0 I I 1	 24 V]	Bus

With pre-wired coil connection LU9M RC

LUL C08				Ca	anopen Module
LU9M RL Pre-wired coil		+	== 24 V		Bus

Basic scheme



Basic scheme



Schneider Electric

Communication modules (continued)

Advantys STB communication module LUL C15 Without pre-wired coil connection



With pre-wired coil connection LU9B N11LC

LUL C15					Advantys	STB Module
LU9B N11L Pre-wired coil	фГ01	0 LI1	 +	24 V	, 	Bus DD In Out

With pre-wired coil connection LU9M RC

LUL C15		Advantys STB Module
LU9M RL O Pre-wired coil O	== 24 V == 24 V + +	

Basic scheme



Profibus DP power supply module LU9 GC7



Parallel wiring modules

Without pre-wired coil connection



With pre-wired coil connection LU9B N11LC

LUF C00	Parallel bus Module
LU9B N11C Pre-wired coil	Link // RJ45 12345678

With pre-wired coil connection LU9M RC

LUF C00	Parallel bus Module
LU9M RC Pre-wired coil	Link // RJ45

Basic scheme



- Forward running 1
- 2 Reverse running Output common
- 3 4 Selector in position (
- 5 Pole state
- 6 Reserved 7 Fault
- 8 Input common

TeSys U starter-controllers



(1) Not connected on connectors X1 to X8. Only present on RJ45 IN and OUT connectors.

(2) 20-way HE10 input connector.

(3) 20-way HE10 output connector.

(4) Wire colours and corresponding HE10 connector pin numbers.

Gateways

LUF P1	Fip I/O	- Modbus Gateway
24 V Aux	X2 Fip I/O	X1 ^(A) 4 5 8

LUF P7	Profibus - Mod	lbus Gateway
24 V Aux	X2 Profibus	X1 (1) (1) (1) (1) (1) (1) (1) (1) (1) (1

DeviceNet -	Modbus Gateway
	<u></u>
X2 DeviceNet	X1 SSS
	X2 DeviceNet

LUF P9

LUF P7

Data profile under AS-Interface

Control unit p	resent in the product			Standard LUCA	 Multifunction LUCM
Status		D0	Ready (available)		
		D1	Poles closed (running)		
Commands		D0	Start - forward running		
		D1	Start - reverse running		

Main registers accessible with Modbus, CANopen, Advantys STB, Profibus DP and DeviceNet communication modules. For other registers and for further information, please consult the User's Manual Communication variables on the website www.schneider-electric.com

. of ouror region		prodoo oorroa				••
Control unit pr	esent in the product			Standard	Advanced	Multifunction
Marking	Register 0Register 99	WordsBits	Commercial reference, serial number, software version			
Log	Register 100Register 450	WordsBits	Fault log, Operating log, Log of last 5 trips			
Status	Register 451Register 464	WordsBits	Alarm signalling (bits), Fault signalling (bits)			
Values	Register 465Register 473	Words	Irms phase 1, phase 2, phase 3. Motor load, thermal status Earth leakage current. Phase imbalance and phase failure			
	Register 474Register 599	WordsBits	Reserved			
Configuration	Register 600Register 699	WordsBits	Protection and alarm thresholds, fallback mode and reset mode			
Commands	Register 700Register 714	WordsBits	Commands			

Status and	Register 452	Bit 0	Short-circuit fault		
values		Bit 1	Overcurrent fault		
		Bit 2	Thermal overload fault		
	Register 455	Bit 0	Ready (available)		
		Bit 1	Poles closed		
		Bit 2	Fault		
		Bit 3	Alarms		
		Bit 4	Tripped ("TRIP" position)		
		Bit 5	Fault acknowledgement allowed		
		Bit 6	Reserved		
		Bit 7	Motor running		
		Bit 8	Motor current % (bit 0)		
		Bit 9	Motor current % (bit 1)		
		Bit 10	Motor current % (bit 2)		
		Bit 11	Motor current % (bit 3)		
		Bit 12	Motor current % (bit 4)		
		Bit 13	Motor current % (bit 5)		
		Bit 14	Reserved		
		Bit 15	Motor starting		
	Register 461	Bit 3	Thermal overload alarm		
	Register 465	Word	Thermal status value		
	Register 466	Word	Motor load value (Im/Ir)		

Configuration	Register 602	Bit 0	Manual reset on thermal overload fault		
		Bit 1	Remote reset on thermal overload fault		
		Bit 2	Automatic reset on thermal overload fault		
	Register 682	Value 0	Fallback mode validation		
		Value 1	Outputs OA1 and OA3 unchanged		
		Value 2	Outputs OA1 and OA3 forced to 0		
		Value 3	Outputs OA1 and OA3 unchanged, signalling existence of communication failure		
		Value 4	Outputs OA1 forced to 1 and OA3 unchanged		
		Value 5	Outputs OA3 forced to 1 and OA1 unchanged		

Commands	Register 700	Bit 0	LO1 output command		
	Register 704	Bit 0	OA1 output command		
		Bit 1	OA3 output command		
		Bit 2	Reserved		
		Bit 3	Faultacknowledgement		
		Bit 4	Reserved		
		Bit 5	Trip test		
		Bit 615	Reserved		

Data accessible

Non-reversing



2-wire control via 2-position switch



3-wire control, pulsed start with maintaining contact







Connection of thermal overload fault signalling modules LUF DA10 Automatic reset Remote reset







Control via Modbus communication module LUL C031 Without pre-wired coil connection



Control via Modbus communication module LUL C033

Without pre-wired coil connection





Basic schemes (continued)

TeSys motor starters - open version TeSys U starter-controllers

Non-reversing

1

Non-reversing starter controllers LUB (continued) Control by communication modules ASILUF C5 and ASILUF C51 Without pre-wired coil connection With local control

Without pre-wired coil connection





With pre-wired coil connection LU9B N11C



Without pre-wired coil connection With local control







Reversing starter-controllers LUB

TeSys motor starters - open version

TeSys U starter-controllers Reversing



2-wire control via 3-position switch



3-wire control, pulsed start with maintaining contact



Control by communication modules ASILUF C5 and ASILUF C51

With pre-wired coil connection LU9M RC With multifunction control unit LUCM



Control by communication modules ASILUF C5 and ASILUF C51

Without pre-wired coil connection

With running direction pilot lights and limit switches



3-wire control, pulsed start with maintaining contact and limit switches





Basic schemes (continued)

TeSys motor starters - open version

TeSys U starter-controllers Reversing

Reversing starter controllers LU2B (continued) Control via Modbus communication module LUL C031

Without pre-wired coil connection. With local control



Reversing starter-controllers LUB + LU6M



3-wire control, pulsed start with maintaining contact



2-wire control via 3-position switch



Without pre-wired coil connection. With local control


Presentation

Soft starters for asynchronous motors Altistart U01 and TeSys U





Presentation

The Altistart U01 is a soft start/soft stop unit for asynchronous motors. It is designed primarily for combinations with **TeSys U** starter-controllers.

When combined with a **TeSys U 1** controller by means of a connector 2, the Altistart U01 3 is a power option which provides the "Soft start/soft stop" function. The result is a unique, innovative motor starter.

Using the Altistart U01 starter enhances the starting performance of asynchronous motors by allowing them to start gradually, smoothly and in a controlled manner. It prevents mechanical shocks, which lead to wear and tear, and limits the amount of maintenance work and production downtime.

The Altistart U01 limits the starting torque and current peaks on starting, on machines which do not require a high starting torque.

The Altistart U01 is designed for the following simple applications:

- Conveyors
- Conveyor belts
- Pumps
- Fans
- Compressors
- Automatic doors and gates
- Small cranes
- Belt-driven machines, etc.

The Altistart U01 is compact and easy to install. It complies with standards IEC/EN 60947-4-2, carries UL, CSA, C-Tick, CCC certifications and C€ marking.

ATSU 01N2eeLT soft start/soft stop units

Control two phases of the motor power supply to limit the starting current and for deceleration

- □ Internal bypass relay
- □ Motor power ratings ranging from 0.75 kW to 15 kW
- □ Motor supply voltages ranging from 200 V to 480 V, 50/60 Hz.
- An external power supply is required for controlling the starter.

Description

- Altistart U01 soft start/soft stop units are equipped with:
- □ A potentiometer for setting the starting time 6
- $\hfill\square$ A potentiometer for setting the deceleration time 8
- A potentiometer for adjusting the start voltage threshold according to the motor
- load 7
- □ 1 green LED 4 to indicate that the unit is switched on

□ 1 yellow LED 5 to indicate that the motor is powered at nominal voltage, if it is connected to the starter

□ A connector 9:

- 2 logic inputs for Run/Stop commands
- 1 logic input for the BOOST function
- 1 logic output to indicate the end of starting

- 1 relay output to indicate the starter has a power supply fault or the motor has reached a standstill at the end of the deceleration stage

	clensu		
ages	1/126	and	1/127

Dimensions:

Description of a TeSys U starter-controller

Please consult the "TeSys U starters - open version" catalogue.

ATSU 01N2•••LT soft start unit functions

2-wire control

The run and stop commands are controlled by a single logic input. State 1 of logic input LI2 controls starting and state 0 controls stopping.



Wiring diagram for 2-wire control

3-wire control

The run and stop commands are controlled by 2 different logic inputs. Stopping is achieved when logic input L11 opens (state 0). The pulse on input L12 is stored until input L11 opens.



Wiring diagram for 3-wire control

Starting time

Controlling the starting time means that the time of the voltage ramp applied to the motor can be adjusted to obtain a gradual starting time, dependent on the motor load.

Voltage boost function via logic input

Activating the BOOST logic input enables the function for supplying a starting overtorque capable of overcoming any mechanical friction. When the input is at state 1, the function is active (input connected to the + 24 V) and

the starter applies a fixed voltage to the motor for a limited time before starting.



Application of a voltage boost equal to 100% of the nominal motor voltage

End of starting

□ Application function for logic output LO1

ATSU 01N2•eLT soft start/soft stop units are equipped with an open collector logic output LO, which indicates the end of starting when the motor has reached nominal speed.

Characteristics:	References:	Dimensions:	Schemes:	
pages 1/126 and 1/127	page 1/128	page 1/129	pages 1/131 to 1/133	
				1/125

Type of starter			ATSU 01N2eeLT
Conformity to standards			Altistart U01 electronic starters have been developed to conform to the strictest international standards and the recommendations relating to electrical industrial control devices (IEC, EN), in particular standard IEC/EN 60947-4-2.
Electromagnetic compatibility	/ EMC		
	Conducted and radiated emissions		CISPR 11 level B, IEC 60947-4-2, level B
	Harmonics		IEC 1000-3-2, IEC 1000-3-4
	EMC immunity		EN 50082-2, EN 50082-1
	Electrostatic discharge		IEC 61000-4-2 level 3
	Immunity to radiated radio- electrical interference		IEC 61000-4-3 level 3
	Immunity to electrical transients		IEC 61000-4-4 level 4
	Voltage/current impulse		IEC 61000-4-5 level 3
	Conducted and radiated emissions		IEC 61000-4-6 level 3
	Immunity to conducted interference caused by radio- electrical fields		IEC 61000-4-11
	Damped oscillating waves		IEC 61000-4-12 level 3
CE marking			The starters carry C€ marking in accordance with the European low voltage directives IEC/EN 60947-4-2.
Product certifications			UL, CSA, C-Tick and CCC
Degree of protection			IP 20
Degree of pollution			2 conforming to IEC/EN 60947-4-2
Vibration resistance			1.5 mm peak to peak from 3 to 13 Hz, 1 gn from 13 to 150 Hz, conforming to IEC/EN 60068-2-6
Shock resistance			15 gn for 11 ms conforming to IEC/EN 60068-2-27
Relative humidity			595% without condensation or dripping water conforming to IEC 60068-2-3
Ambient temperature around	Storage	°C	- 25+ 70 conforming to IEC/EN 60947-4-2
the unit	Operation	°C	- 10+ 40 without derating, up to 50°C with current derating of 2% per °C above 40°C
Maximum operating altitude		m	1000 without derating (above this, derate the current by 2.2% per additional 100 m)
Operating position Maximum permanent angle in re mounting position	elation to the normal vertical		

Electrical characteri	01100								
Type of starter			ATSU 01N2	•LT					
Category of use	Conforming to IEC 60947-4-2		Ac-53b						
Rated operating voltage	3-phase \sim voltage	v	200 - 10% to 480 + 10%						
Frequency		Hz	50 - 5% to 60 + 5%						
Output voltage			Maximum 3-p	hase voltage e	equal to lin	e supply v	oltage		
Control supply voltage			24 V, 100 m	A ± 10%					
Rated operating current		Α	632						
Adjustable starting time		s	110						
Adjustable deceleration time		s	110						
Starting torque		%	30 80% of E	OOL motor star	rting torqu	е			
Type of starter	ATSU		01N206LT	01N209LT	01	1212LT	01N2	22LT	01N232LT
Control power supply consum	nption		24 V, 65 m/	4			24 V :	 , 100 m	A
Power dissipated	At full load at end of starting	w	1.5	1.5	1.5		2.5		2.5
	In transient state at 5 times the rated operating current	w	61.5	91.5	121	.5	222.5		322.5
Type of starter			ATSU 01N206	LT to ATSU 0 ²	1N222LT	ATS	U 01N232	2LT	
Use									
Starting time	Starting time	s	1	5	10	1		5	10
Full voltage state or starter at standstill	Maximum number of cycles per hour		100	20	10	50		10	5
Operating cycle									

	ntation: 1/124 and 1/125	References: page 1/128	Dimensions: page 1/129	Schemes: pages 1/130 to 1/133	
1/12	6		Schneider		

Characteristics (continued)

Soft starters for asynchronous motors Altistart U01 and TeSys U

Electrical char	acteristics (continued)	
Logic input power sup and control) + 24 V, COM	oply (electrically isolated between power	24 V ± 10% Isolated Max. current 100 mA
Logic inputs LI1, LI2, BOOST Stop, run and boost on s	start-up functions	Logic inputs with impedance 27 k Ω ; 24 V power supply (U max 40 V) Max. current 8 mA State 0 if U < 5 V and I < 0.2 mA State 1 if U > 13 V and I > 0.5 mA
Logic output LO1 End of starting signal		Open collector logic output: External 24 V power supply (minimum 6 V, maximum 30 V) Max. current 200 mA
Relay output R1A R1C		Normally open (N/O) contact Minimum switching capacity: 10 mA for 6 V $=$ Maximum switching capacity on inductive load (cos φ = 0.5 and L/R = 20 ms): 2 A for 250 V \sim or 30 V $=$ (AC-15) Maximum operating voltage 440 V
LED signalling	Green LED	Starter powered up
	Yellow LED	Nominal voltage reached

Connections (maximum connection capacity and tightening torque

Connections (maxime	in connection capacity and t	ignienn	ig torque)	
Power circuit			Connection	n to Ø 4 mm screw clamps
Flexible wire without cable	1 conductor	mm²	1.510	8 AWG
end	2 conductors	mm ²	1.56	10 AWG
Flexible wire with cable end	1 conductor	mm ²	16	10 AWG
	2 conductors	mm ²	16	10 AWG
Rigid wire	1 conductor	mm ²	110	8 AWG
	2 conductors	mm ²	16	10 AWG
Tightening torque		N.m	1.92.5	
Control circuit			Screw conr	nector
Flexible wire without cable	1 conductor	mm²	0.52.5	14 AWG
end	2 conductors	mm ²	0.51.5	16 AWG
Flexible wire with cable end	1 conductor	mm ²	0.51.5	16 AWG
	2 conductors	mm ²	0.51.5	16 AWG
Rigid wire	1 conductor	mm ²	0.52.5	14 AWG
	2 conductors	mm ²	0.51	17 AWG
Tightening torque		N.m	0.5	

Torque characteristics (typical curves)



The diagram opposite shows the torque/speed characteristic of a cage motor in relation to the supply voltage.

The torque varies in line with the square of the voltage at a fixed frequency. The gradual increase in the voltage prevents the instantaneous current peak on power-up.

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Presentation:	References:	Dimensions:	Schemes:	
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ATSU 01N222LT





ATSU 01N200LT

Soft start/soft stop units for 0.75 to 15 kW motors

(car	n be comb	ined with the	TeSys U star	ter-controlle	r)	
Moto	or			Starter		
Moto	or power (1)		Nominal	Reference	Weight
230	V 230 V	400 V	460 V	current		
kW	HP	kW	HP	Α		kg
3-ph	nase supp	oly voltage: 20	0480 V 50/	60 Hz		
0.75 1.1	1 1.5	1.5 2.2 3	2 3	6	ATSU 01N206LT	0.340
1.5 -	2	_ 4	5 -	9	ATSU 01N209LT	0.340
2.2 3	3 -	5.5 -	7.5	12	ATSU 01N212LT	0.340
4 5.5	5 7.5	7.5 11	10 15	22	ATSU 01N222LT	0.490
7.5	10	15	20	32	ATSU 01N232LT	0.490

Accessorie			
Description	Used for starter	Reference	Weight kg
Power connector between ATSU 01N2●●LT and TeSvs U	ATSU 01N2eeLT	VW3 G4104	0.020

TeSys U starter and soft start unit combinations

Numerous possibilities for combinations and options are offered. Please consult the "TeSys U Starters-open version" specialist catalogue.

Motor po	ower		power Soft starter		TeSys U	TeSys U		
Voltage				Power base	Control unit (2)			
230 V kW/ <i>HP</i>	400 V kW	460 V <i>HP</i>						
0.75/1	1.5	2	ATSU 01N206LT	LUB 12	LUC• 05BL			
1.1/1.5	2.2/3	3	ATSU 01N206LT	LUB 12	LUCe 12BL			
1.5/2	-	-	ATSU 01N209LT	LUB 12	LUCe 12BL			
-	4	5	ATSU 01N209LT	LUB 12	LUC• 12BL			
2.2/3	-	_	ATSU 01N212LT	LUB 12	LUCe 12BL			
3/—	5.5	7.5	ATSU 01N212LT	LUB 32	LUCe 18BL			
4/5	7.5	10	ATSU 01N222LT	LUB 32	LUCe 18BL			
5.5/7.5	11	15	ATSU 01N222LT	LUB 32	LUC• 32BL			
7.5/10	15	20	ATSU 01N232LT	LUB 32	LUC• 32BL			

Example of a starter-motor combination with:

1 non-reversing power base for DOL starting (LUB•2BL)

2 control unit (LUCM ●●BL)

3 power connector (VW3 G4104) 4 Altistart U01soft start/soft stop unit (ATSU 01N2••LT)

(1) Standard motor power ratings, HP power ratings indicated according to standard UL 508.

(2) Depending on the configuration of the chosen TeSys U starter-controller, replace the • with A for standard, B for expandable, and M for multifunction.

Presentation: pages 1/124 and 1/125

Dimensions page 1/129 Schemes: pages 1/130 to 1/133

TeSys U combination (non-reversing power base) and ATSU 01N206LT to ATSU 01N212LT Mounting on Lr (35 mm) rail with VW3 G4104 connector



TeSys U combination (non-reversing power base) and ATSU 01N222LT to ATSU 01N232LT

Mounting on Lr (35 mm) rail with VW3 G4104 connector



VW3 G4104 connector



Presentation:

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Characteristics:

pages 1/126 and 1/127

TeSys U combination (non-reversing or reversing power base) and ATSU 01N206LT to ATSU 01N212LT
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TeSys U combination (non-reversing or reversing power base) and ATSU 01N222LT to ATSU 01N232LT Side by side mounting





References

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For 0.75 to 15 kW motors



	Compatible components (For full references, Please consult our catalogue and Please consult our catalogue or refer to our catalogue: "Motor starter				
solutions - 0	solutions - Control and protection components")				
Code	Description				
A1	Soft start/soft stop unit				
QF1	TeSys U controller-starter				
CU	TeSys U control unit				

References: page 1/128

For 0.75 to 15 kW motors

ATSU 01N2eeLT soft start/soft stop units (continued)

Automatic 2-wire control Without deceleration





Functional diagrams





Automatic 3-wire control



With deceleration



Functional diagrams





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A1: Soft start/soft stop unit S1, S2: XB4 B or XB5 B pushbuttons

QF1: TeSys U controller-starter

t1: Acceleration time can be controlled by a potentiometer t2: Deceleration time can be controlled by a potentiometer

0 ₁ . Starting	unie can be co	initioned by a	polenilomelei	

Presentation:	Characteristics:	References:	Dimensions:	
pages 1/124 and 1/125	pages 1/126 and 1/127	page 1/128	page 1/129	

For 0.75 to 15 kW motors

ATSU 01N2••LT soft start/soft stop units (continued)

Automatic 3-wire control, with reversing unit

With deceleration





QF1: TeSys U controller-starter with reversing unit

A1: Soft start/soft stop unit

S1, S2, S3: XB4 B or XB5 B pushbuttons S3: minimum depression time 500 ms

Boost on starting and end of starting signal



A1: Soft start/soft stop unit

QF1: TeSys U controller-starter with reversing unit A1: Soft start/soft stop unit

S1, S2, S3: XB4 B or XB5 B pushbuttons

Presentation: pages 1/124 and 1/125	Characteristics: pages 1/126 and 1/127	References: page 1/128	Dimensions: page 1/129	
pages in 124 and in 125			page 1/123	

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Schneider Blectric

For 0.75 to 15 kW motors

ATSU 01N2eeLT soft start/soft stop units (continued)

Automatic control with Modbus communication module, with and without deceleration Without reversing unit







Register	Bit	Value				
Powering down TeSys U and ATSU						
704	0	0				
Automatic control without deceleration						
700	0	1				
704	0	0				
Automatic control with deceleration						
700	0	1				
700	0	0				
	TeSys U and ATSU 704 bl without decelera 700 704 bl with deceleratio 700	TeSys U and ATSU 704 0 pl without deceleration 700 0 704 0 pl with deceleration 700 0				

Function	Register	Bit	Value	
	•		value	
Powering up 1	eSys U and ATSU			
Forward	704	0	1	
Reverse	704	1	1	
Powering dow	n TeSys U and AT	SU		
Forward	704	0	0	
Reverse	704	1	0	
Automatic con	trol without dece	eleration		
Run	700	0	1	
Stop forward	704	0	0	
Stop reverse	704	1	0	
Automatic control with deceleration (forward or reverse)				
Run	700	0	1	
Soft stop	700	0	0	
A1: Soft start/soft stop unit				

A1: Soft start/soft stop unit

QF1: TeSys U controller-starter with reversing unit

Automatic control with AS-Interface communication module, without deceleration Without reversing unit With reversing unit



Function	Bit	Value	
Power-up and automa	tic control without dece	eleration	
Run	D0	1	
Stop	D0	0	

Characteristics:

pages 1/126 and 1/127

A1: Soft start/soft stop unit

pages 1/124 and 1/125

Presentation:



Function	Bit	Value	
Power-up and automati	c control without dece	leration	
Run forward	D0	1	
Stop	D0	0	
Run reverse	D1	1	
Stop	D1	0	

A1: Soft start/soft stop unit

QF1: TeSys U controller-starter with reversing unit

Dimensions:

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References:

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Presentation, description, references

TeSys motor starters - open version

Magnetic control unit for the protection of variable speed controllers and soft start units



Presentation

When installed upstream of a variable speed controller or soft start unit, control unit LUCLee, used in conjunction with an LUB 12 or LUB 32 power base, provides:

- . isolation,
- □ short-circuit protection of the motor starter.

(variable speed controller-based or soft start unit-based motor starters).

Note: control unit LUCL, when used in conjunction with power base LUB 12 or LUB 32, conforms to standard IEC 60947-2.

Installation regulations

When the length of the cable between the TeSys U starter and the variable speed controller is more than 1.5 m, the c.s.a. of the cable between the variable speed controller and the TeSys U starter (S2) must be equal to the c.s.a. of the cable upstream of TeSys U (S1).



Description

- 1 Extraction and locking handle
- 2 Sealing of locking handle
- 3 Dial for magnetic adjustment of motor In
- 4 Locking of settings by sealing the transparent cover

References			
Description	Line current of the variable speed cont or soft start unit	roller (1)	Weight
	Α		kg
Magnetic control unit	0.150.6	LUCLX600	0.135
	0.351.4	LUCL1X.	0.135
	1.255	LUCL0500	0.135
	312	LUCL1200	0.135
	4.518	LUCL18	0.135
	832	LUCL32	0.135
(1) Standard control circuit	voltage:		
Volts 24	4872 110	240	

voits	24	40/2	110240
	BL (2), (3)	-	-
\sim	В	-	-
$$ or \sim	_	ES (4)	FU (5)

(2) Voltage code to be used for a starter-controller with communication module.

(3) d.c. voltage with maximum ripple of ± 10 %. (4) ---: 48...72 V, ∼: 48 V. (5) ---: 110...220 V, ∼: 110...240 V.

TeSys motor starters - open version Magnetic control unit for the protection of

variable speed controllers and soft start stop units

Functions provided	Maximum motor power ratings 50/60 Hz			Power base reference	Control unit reference	Line current
	< 400/415 V	500 V	690 V			
	KW	KW	ĸw			Α
 Short-circuit protection Manual reset 	0.09	-	-	LUB 12 or LUB 32	LUCLX600	0.150.6
	0.25	_	_	LUB 12 or LUB 32	LUCL1X.	0.351.4
	1.5	2.2	3	LUB 12 or LUB 32	LUCL05.	1.255
	5.5	5.5	9	LUB 12 or LUB 32	LUCL12.	312
	7.5	9	15	LUB 32	LUCL18	4.518
	15	15	18.5	LUB 32	LUCL32.	832

	Standard	Advanced			Multifunction	
	LUCA	LUCB	LUCC	LUCD	LUCL	LUCM
ion		'				
Over current protection		etting current			_	3 to 17 x the setting current
Short-circuit protection		nax. current				
loss						
imbalance						
uipment protection only)						
Tripping class			10	20		530
Motor type			Single-phase	3-phase	Single-phas	e and 3-phase
iction						
Manual						Parameters can be set
Automatic or remote		With function module, or parameters can				Parameters can be set
		be set via the bus with a communication module (see page 1/68).		Parameters can be se via the bus with a communication modul (see page 1/68).		
		LUCA ion 14.2 x the s 14.2 x the n 14.2 x the n loss 14.2 x the n imbalance 10 uipment protection only) 10 3-phase inction 10 Manual 10	LUCA LUCB ion 14.2 x the setting current 14.2 x the setting current 14.2 x the max. current loss 10 3-phase 10 action 10 Manual 10 Automatic or remote With function	LUCA LUCB LUCC ion 14.2 x the setting current 14.2 x the max. current 14.2 x the max. current loss 14.2 x the max. current imbalance 10 uipment protection only) 10 10 10 3-phase Single-phase Inction Inction Manual With function module, or pa be set via the bus with a correct	LUCA LUCB LUCC LUCD ion 14.2 x the setting current 14.2 x the setting current 10 14.2 x the max. current 14.2 x the max. current loss 14.2 x the max. current 10 imbalance 10 10 20 a-phase Single-phase 3-phase Manual Manual With function module, or parameters carrent be set via the bus with a communication	LUCA LUCB LUCC LUCD LUCL ion 14.2 x the setting current 14.2 x the setting current 14.2 x the max. current loss 14.2 x the max. current 14.2 x the max. current loss 14.2 x the max. current 14.2 x the max. current loss 14.2 x the max. current 14.2 x the max. current loss 14.2 x the max. current 10 imbalance 10 10 20 inpendent protection only) 10 20 3-phase Single-phase 3-phase Single-phase 3-phase Single-phase Manual Manual Vith function module, or parameters can be set via the bus with a communication

Compatibility of		References	Functions
control unit LUCLee with		References	runcions
The starter-controller	Yes	LUB 12/LUB 32	Starter-controller (magnetic protection)
he starter	No	LUS 12/LUS 32	Starter without either magnetic or thermal overload protection)
The controller	No	LUT M	Controller (without thermal overload protection)
Add-on contact blocks	Yes	LUA 1C11	Add-on contact blocks with fault signalling (1 N/O + 1 N/C)
with fault signalling and auxiliary contacts		LUA 1C20	Add-on contact blocks with fault signalling (2 N/O)
and auxiliary contacts		LUF N20	Auxiliary contacts (2 N/O)
		LUF N11	Auxiliary contacts (1 N/O + 1 N/C)
		LUF N02	Auxiliary contacts (2 N/C)
Communication modules	Yes	ASILUF C5 and ASILUF C51	AS-Interface communication modules
		LUF C00	Parallel wiring module
		LUL C033	Modbus communication module (1 output/2 inputs)
		LUL C031	Modbus communication module (1 output)
		LUL C15	Advantys STB communication module (1 output/2 inputs)
		LUL C08	CANopen communication module (1 output/2 inputs)
		LUL C09	DeviceNet communication module (1 output/2 inputs)
		LUL C07	Profibus DP communication module (1 output/2 inputs)
Function modules	No	LUF W10	Alarm function module
		LUF DH11	Thermal overload signalling module with manual reset
		LUF DA01	Thermal overload signalling module with automatic or remote reset (1 N/C)
		LUF DA10	Thermal overload signalling module with automatic or remote reset (1 N/O)
		LUF V2	Motor load indication module

Characteristics

TeSys motor starters - open version TeSys U starter-controllers

	agnetic control unit LU			
Protection	Motor type		3-phase	
	Conforming to standard		When used in conjunction with an LUB 12 unit LUCL conforms to standard IEC 6094	
Short-circuit protection	Tripping threshold		14.2 x In (max. setting current)	
	Tripping tolerance		±20 %	
Environment				
Product certifications			CE	
Conforming to standards			When used in conjunction an LUB power b standard 60947-2.	base, control unit LUCL conforms to
Rated insulation voltage (Ui)	Conforming to IEC/EN 60947-1, overvoltage category III, degree of pollution: 3	v	690	
Rated impulse withstand voltage (Uimp)	Conforming to IEC/EN 60947-2	kV	6	
Safety separation of circuits	Conforming to IEC/EN 60947-1	v	Between the control or auxiliary circuit and	the main circuit: 400
SELV	appendix N		Between the control and auxiliary circuits:	40
Degree of protection Conforming to IEC/EN 60947-1	Front panel outside connection zone		IP 40	
protection against	Front panel and wired terminals		IP 20	
lirect finger contact)	Other faces		IP 20	
Protective treatment	Conforming to IEC/EN 60068		"TH"	
	Conforming to/EN 60068-2-30	Cycles	12	
	Conforming to IEC/EN 60068-2-11	h	48	
Ambient air temperature	Storage	°C	- 40+ 85	
round the device	Operation	°C	Power bases and standard and advanced (At temperatures above 60°C and up to 70 9 mm between products).	
			Power bases and multifunction control unit (At temperatures above 45 °C, leave a min At temperatures above 55 °C up to 60 °C, l	imum gap of 9 mm between products.
Maximum operating altitude		m	2000	
Operating positions	In relation to normal vertical mounting plane			
-lame resistance	Conforming to UL 94		V2	
	Conforming to IEC/EN 60695-2-12	°C	960 (parts supporting live components)	
		°C	650	
Environmental restrictions			Cadmium and silicone-free, recyclable	
Shock resistance /2 sine wave = 11 ms	Conforming to IEC/EN60068-2-27 (1)		Power poles open: 10 gn Power poles closed: 15 gn	
/ibration resistance 5300 Hz	Conforming to IEC/EN 60068-2-6 (1)		Power poles open: 2 gn Power poles closed: 4 gn (2)	
Resistance to	Conforming to IEC/EN 61000-4-2	kV	In open air: 8 - Level 3	
electrostatic discharge		kV	On contact: 8 - Level 4	
mmunity to radiated high- requency disturbance	Conforming to IEC/EN 61000-4-3	V/m	10 - Level 3	
mmunity to ast transient currents	Conforming to IEC/EN 61000-4-4	kV	All circuits except for serial link: 4 - Level 4	
		kV	Serial link: 2 - Level 3	
mmunity to dissipated shock waves	Conforming to IEC/EN 60947-2		Common mode	Serial mode
	Uc \sim 24240 V, Uc = 48220 V	kV	2	1
	UC 40220 V			
	$\frac{0c = 24 \text{ V}}{0c = 24 \text{ V}}$		Not applicable	

(2) 2 gn with Advantys STB or CANopen communication modules.

TeSys motor starters - open version TeSys U starter-controllers Power bases and LUCL magnetic control unit

Power base and control unit			LUB 12 + LUCL	LUB 32 + LUCL
Power circuit conne	ction characteristics			
Connection to Ø 4 mm sc	rew clamp terminals			
Flexible cable	1 conductor	mm ²	2.510	2.510
without cable end	2 conductors	mm ²	1.56	1.56
Flexible cable	1 conductor	mm ²	16	16
with cable end	2 conductors	mm ²	16	16
Flexible cable	1 conductor	mm ²	110	110
without cable end	2 conductors	mm ²	16	16
Screwdriver			Philips n° 2 or flat screwdriver: Ø 6 mm	
Tightening torque		N.m	1.92.5	1.92.5
Control circuit conn	ection characteristics			
Connection to Ø 3 mm sc	rew clamp terminals			
Flexible cable	1 conductor	mm ²	0.751.5	0.751.5
without cable end	2 conductors	mm ²	0.751.5	0.751.5
Flexible cable	1 conductor	mm ²	0.341.5	0.341.5
with cable end	2 conductors	mm ²	0.341.5	0.341.5
Flexible cable	1 conductor	mm ²	0.751.5	0.751.5
without cable end	2 conductors	mm ²	0.751.5	0.751.5
Screwdriver			Philips n° 2 or flat screwdriver: Ø 5 mm	
Tightening torque		N.m	0.81.2	0.81.2
Control circuit chara	actoristics		in the second	•
Rated control		v	24 240	24240
Rated control circuit voltage	~ 50/60 Hz	V	24240 24220	24240
Voltage limits	 24 V (1)	v	2027	2027
Operation	\sim 24 V	V	2026.5	2027
operation	\sim or == 4872 V	v	~ 38.572. == 38.593	~ 38.572 38.593
	~110240 V	v	~ 88264	~ 88264
		V		
Drop-out	24 V	V	14.5	14.5
	\sim 24 V	v	14.5	14.5
	~ or == 4872 V	v	29	29
	~ 110240 V, == 110220 V	V	55	55
Typical consumption	24 V	mA	130	220
I max while closing	\sim 24 V	mA	140	220
	\sim or $=$ 4872 V	mA	280	280
	\sim 110240 V, == 110220 V	mA	280	280
I rms sealed	24 V	mA	60	80
	\sim 24 V	mA	70	90
	<u>~ or </u>	mA	35	45
	\sim 110240 V, = 110220 V	mA	35	25
Heat dissipation		w	2	3
Operating time	Closing	ms	24 V: 70; 48 V: 60; ≥ 72 V: 50	24 V: 70; 48 V: 60; ≥ 72 V: 50
	Opening	ms	35	35
Resistance to micro-breaks	150/5N 04000 4 44	ms	3	3
Resistance to voltage dips Mechanical durability	IEC/EN 61000-4-11		At least 70 % of Uc for 500 ms	15
Mechanical durability Maximum operating rate	In millions of operating cycles		3600	3600
·		1		
Main pole character	151105			
Number of poles	Describe		3	3
Isolation conforming to IEC/EN 60947-1	Possible		Yes	Yes
-	Padlocking	•	1 padlock with Ø 6.9 mm shank	1 padlock with Ø 6.9 mm shank
Rated thermal current	Conforming Cotogon AC 11	A	12 R < 70 °C: 12 A	32
Rated operational current $(Ue \leq 440 V)$	Conforming Category AC-41		θ ≤ 70 °C: 12 A	θ ≤ 70 °C: 32 A
/	to IEC/ EN Category AC-43 60947-2		θ ≤ 70 °C: 12 A	θ ≤ 70 °C: 32 A
Rated operational voltage		V	690 (3)	690 <i>(3)</i>
Frequency limits	Of the operating current	Hz	4060	4060
in intervence in intervence	Operational current	Α	3 6 9 12 18 25 32	
Power dissipated		14/	0.1 0.3 0.6 1.1 2.4 4.6 7.5	
Power dissipated in the power circuits	Power dissipated	w		
Power dissipated				
Power dissipated	Power dissipated in all three poles	V	230 440 500 600	
Power dissipated in the power circuits Rated breaking capacity on sl	Power dissipated in all three poles	V kA	230 440 500 600 50 50 10 4	
Power dissipated in the power circuits Rated breaking capacity on sl Total breaking time	Power dissipated in all three poles hort-circuit	V kA ms	230 440 500 600 50 50 10 4 2 2 2 2	1
Power dissipated in the power circuits	Power dissipated in all three poles	V kA ms kA ² s	230 440 500 600 50 50 10 4 2 2 2 2 90	120
Power dissipated in the power circuits Rated breaking capacity on sl Total breaking time	Power dissipated in all three poles hort-circuit	V kA ms kA ² s (1) d.c. v	230 440 500 600 50 50 10 4 2 2 2 2	120

TeSys motor starters - open version TeSys U starter-controllers

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Coordination

The standard defines tests at different levels of current; the purpose of these tests is to place the equipment in extreme conditions.

The standard defines 2 types of coordination, according to the condition of the components after testing: type 1 and type 2

Type 1 coordination requires that in a short-circuit condition, the contactor or starter must not present any danger to personnel or installations and must not be able to resume operation without repair or the replacement of parts.

The product combinations given below provide type 1 coordination

Soft start-soft stop unit/TeSysU starter controller combination with magnetic protection

TeSys U / Altistart 48: type 1 coordination				
Power	TeSys U references	Soft start unit reference		
400 V (kW) (protection + power switching)	Class 10	Class 20		
5.5	LUB32 + LUCL32 or LUCL18	-	ATS48D17	
7.5	LUB32 + LUCL32	ATS48D17	ATS48D22	
11	LUB32 + LUCL32	ATS48D22	ATS48D32	
15	LUB32 + LUCL32	ATS48D32	ATS48D38	
10	LUBJZ + LUGLJZ	A1340D32	A1 340D 30	

Variable speed controller/TeSysU starter controller combination with magnetic protection

with may	with magnetic protection				
TeSys U / A	ltivar 21 UL Type 1/IP 20: type 1	coordination			
Power 400 V (kW)	TeSys U references (protection + power switching)	Variable speed controller reference			
0.75	LUB12 + LUCL05	ATV21H075N4			
		ATV21HU15N4			
2.2	LUB12 + LUCL12	ATV21HU22N4			
3	LUB12 + LUCL12	ATV21HU30N4			
4	LUB12 + LUCL12	ATV21HU40N4			
5.5	LUB32 + LUCL32 or LUCL18	ATV21HU55N4			
7.5	LUB32 + LUCL32 or LUCL18	ATV21HU75N4			
11	LUB32 + LUCL32	ATV21HD11N4			
15	LUB32 + LUCL32	ATV21HD15N4			

TeSys U / A	ltivar 21 IP 54: type 1 coordinat	ion
Power 400 V (kW)	TeSys U references (protection + power switching)	Variable speed controller reference
0.75	LUB12 + LUCL05	ATV21W075N4/N4C
1.5	LUB12 + LUCL12 or LUCL05	ATV21WU15N4/N4C
2.2	LUB12 + LUCL12	ATV21WU22N4/N4C
3	LUB12 + LUCL12	ATV21WU30N4/N4C
4	LUB12 + LUCL12	ATV21WU40N4/N4C
5.5	LUB32 + LUCL32 or LUCL18	ATV21WU55N4/N4C
7.5	LUB32 + LUCL32 or LUCL18	ATV21WU75N4/N4C
11	LUB32 + LUCL32	ATV21WD11N4/N4C
15	LUB32 + LUCL32	ATV21WD15N4/N4C

Combinations

TeSys motor starters - open version TeSys U starter-controllers

Variable speed controller/TeSysU starter controller combination

with magnetic protection (continued)

TeSys U / Altistart 31: type 1 coordination

LUB12 + LUCL05

Power

0.37

400 V (kW)

TeSys U references

(protection + power switching)



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			And the set

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7.5	LUB32 + LUCL32	ATV31HU75N4
TeSys U / A	Atistart 61: type 1 coordination	
Power 400V (kW)	TeSys U references (protection + power switching)	Variable speed controller reference
0.75	LUB12 + LUCL05	ATV61H075N4
1.5	LUB12 + LUCL12	ATV61HU15N4
2.2	LUB12 + LUCL12	ATV61HU22N4
3	LUB32 + LUCL18	ATV61HU30N4
4	LUB32 + LUCL18	ATV61HU40N4
5.5	LUB32 + LUCL32	ATV61HU55N4
7.5	LUB32 + LUCL32	ATV61HU75N4
TeSys U / A	Altistart 71: type 1 coordination	
Power 400V (kW)	TeSys U references (protection + power switching)	Variable speed controller reference
0.75	LUB12 + LUCL05	ATV71H075N4
1.5	LUB12 + LUCL12	ATV71HU15N4
2.2	LUB12 + LUCL12	ATV71HU22N4
3	LUB32 + LUCL18	ATV71HU30N4
4	LUB32 + LUCL18	ATV71HU40N4
5.5	LUB32 + LUCL32	ATV71HU55N4

Variable speed controller reference

ATV31H037N4